

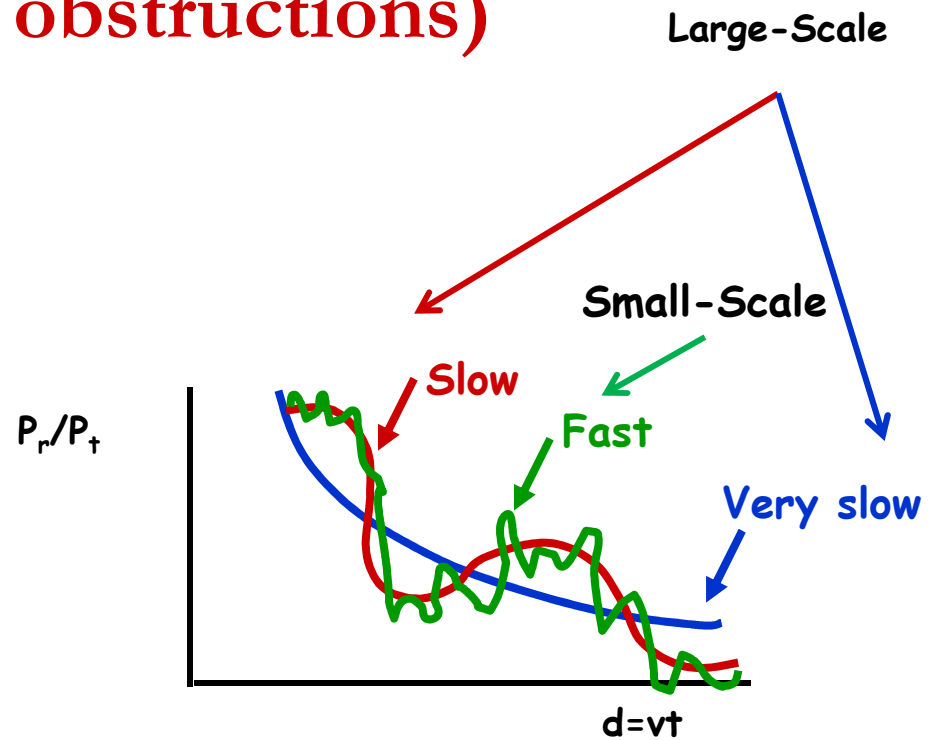
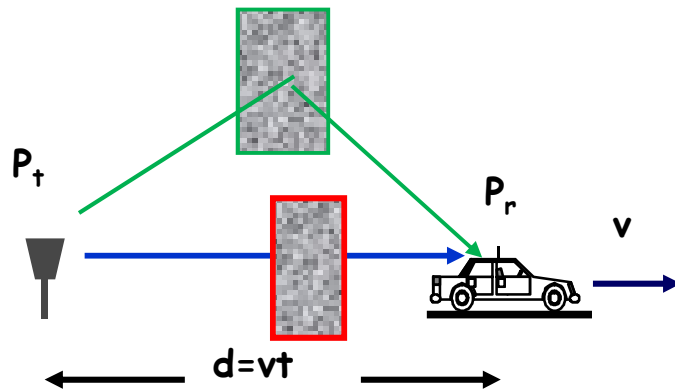
# Wireless Communications

## Lecture 4

### Small-Scale Fading

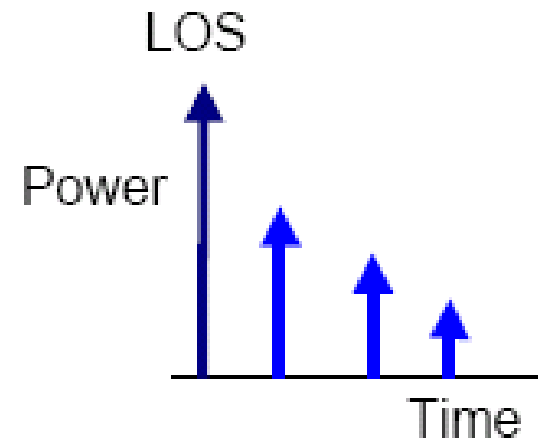
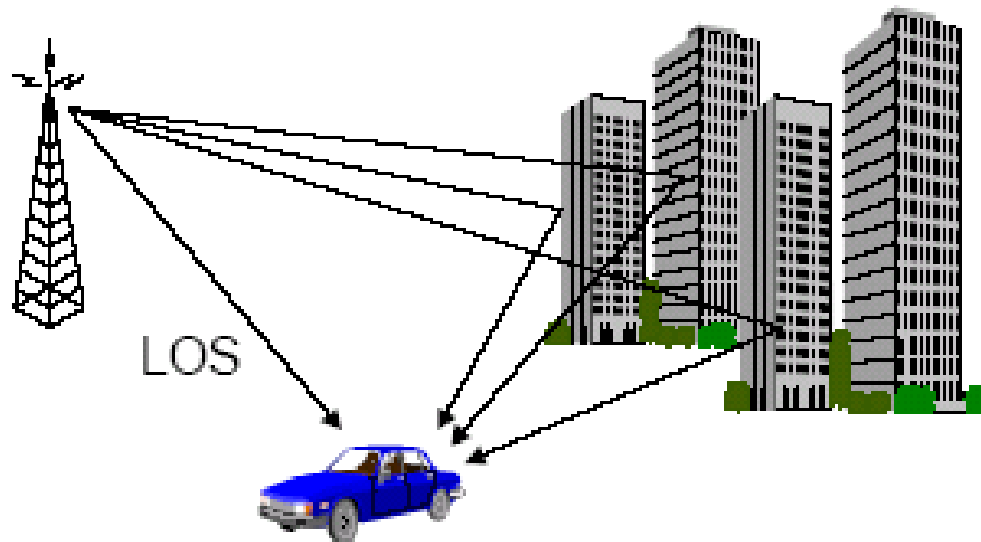
# Propagation Characteristics

- Path Loss (includes average shadowing)
- Shadowing (due to obstructions)
- Multipath Fading



# Multipath Propagation

- Multiple waves arrive at the receiver
  - Delay spread
  - Doppler shift
  - Angle spread
- Influencing factors
  - Speed of the mobile
  - Speed of surrounding objects
  - Signal bandwidth



Multipath Power  
Delay Profile

# Small-Scale Fading

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- ◆ Multipath signals have randomly distributed amplitudes, phases, & direction of arrival
    - Vector summation ( $A \angle \theta$ ) @ Rx of multipath leads to constructive/destructive interference as mobile Rx moves in space (time)
    - RSS can vary by 20–30 dB over distances of only  $\lambda / 4$  !
    - $\lambda / 4 \rightarrow \sim 5\text{--}10$  cm or 3–5 msec (for  $v = 40$  mph)
    - Fading occurs about RSS predicted from large-scale path loss models
  - ◆ Even fixed Tx/Rx wireless links can experience fading due to motion of objects (cars, people, trees, etc.) in surrounding environment
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# Mobile Radio Channel

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## ◆ Physical Factors Influencing Fading in Mobile Radio Channel (MRC)

### 1) Multipath Propagation

- Number and strength of multipath signals
- Time delay of signal arrival
  - » Large path differences → large delay
- Urban area w/ many buildings distributed over large spatial scale
  - » Large # of strong multipath signals with a few having large time delay
- Suburb with nearby office park or shopping mall
  - » Moderate # of strong multipath signals with small → moderate delay times
- Rural → few multipath signals (LOS + ground reflection)

# Mobile Radio Channel

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## ◆ Physical Factors Influencing Fading in Mobile Radio Channel (MRC)

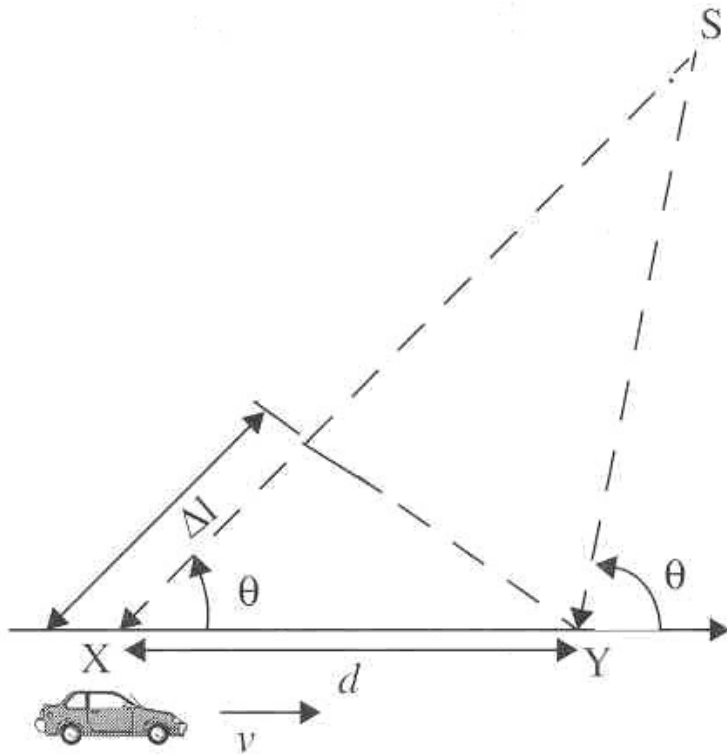
### 2) Speed of Mobile

- Relative motion between base station & mobile causes random frequency modulation due to Doppler shift ( $f_d$ )

$$\gg f_d = (v/\lambda) \cos \theta$$

- Multipath signals will have different  $f_d$ 's for constant  $v$  b/c of random arrival directions ( $\theta$ )!!

# Doppler Shift



$$f_d = (v/\lambda) \cos \theta \quad \text{where}$$

$v$  : velocity (m/s)

$\lambda$  : wavelength (m)

$\theta$  : angle between mobile direction  
and arrival direction of RF energy

+ shift  $\rightarrow$  mobile moving toward S

- shift  $\rightarrow$  mobile moving away from S

# Mobile Radio Channel

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- ◆ Physical Factors Influencing Fading in Mobile Radio Channel (MRC)

## 3) Speed of Surrounding Objects

- Also generates multipath signals with Doppler shift
- Dominates small-scale fading if speed of objects  $>$  mobile speed
  - » Otherwise ignored



# Mobile Radio Channel

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## ◆ Physical Factors Influencing Fading in Mobile Radio Channel (MRC)

### 4) Tx Signal Bandwidth ( $B_s$ )

- MRC modeled as filter w/ specific bandwidth (BW)
- Relationship between signal BW & MRC BW will determine:
  - a) if small-scale fading is significant
  - b) if time distortion of signal leads to inter-symbol interference (ISI)

# MRC Impulse Response

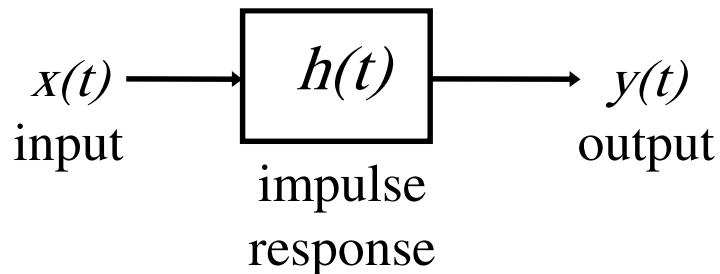
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- ◆ Model MRC as linear filter with \*\* time-varying \*\* impulse response
- ◆ Filter model due to vector summation of random amplitudes & phases of multipath signals
- ◆ Time variation due to mobile motion → time delay of multipath signals varies with location of Rx!
- ◆ MRC has fundamental bandwidth limitation → model as BPF

# MRC Impulse Response

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## ◆ Linear filter theory



$$y(t) = x(t) \otimes h(t)$$

or

$$Y(f) = X(f) \cdot H(f)$$

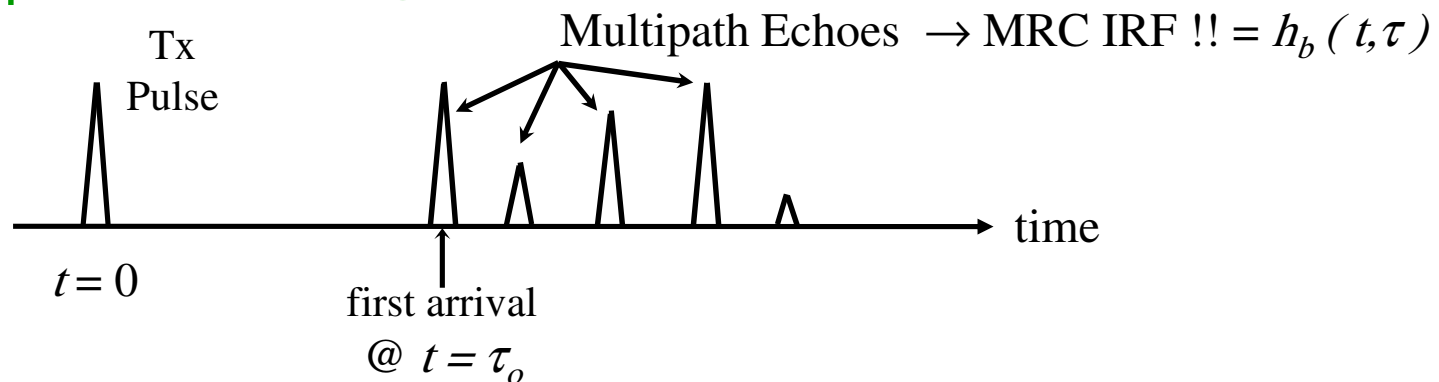
## ◆ How is unknown $h(t)$ determined?

- Let  $x(t) = \delta(t) \rightarrow$  delta or impulse input then
- $y(t) = h(t) \rightarrow$  impulse response function (IRF)
- IRF for standard filter theory is the same regardless of when it is measured  $\rightarrow$  **time invariant!**

# MRC Impulse Response

## ◆ How is IRF of MRC determined?

- “Channel sounding” → Radar → Fig. 5.6, pg. 192
- Transmit short time duration pulse (wide BW) and record multipath echoes @ Rx



- » Short duration Tx pulse  $\approx$  unit impulse  $\delta(t)$  !
- » Define excess delay time as  $\tau$  where  $t > \tau_o$

# Channel Sounding

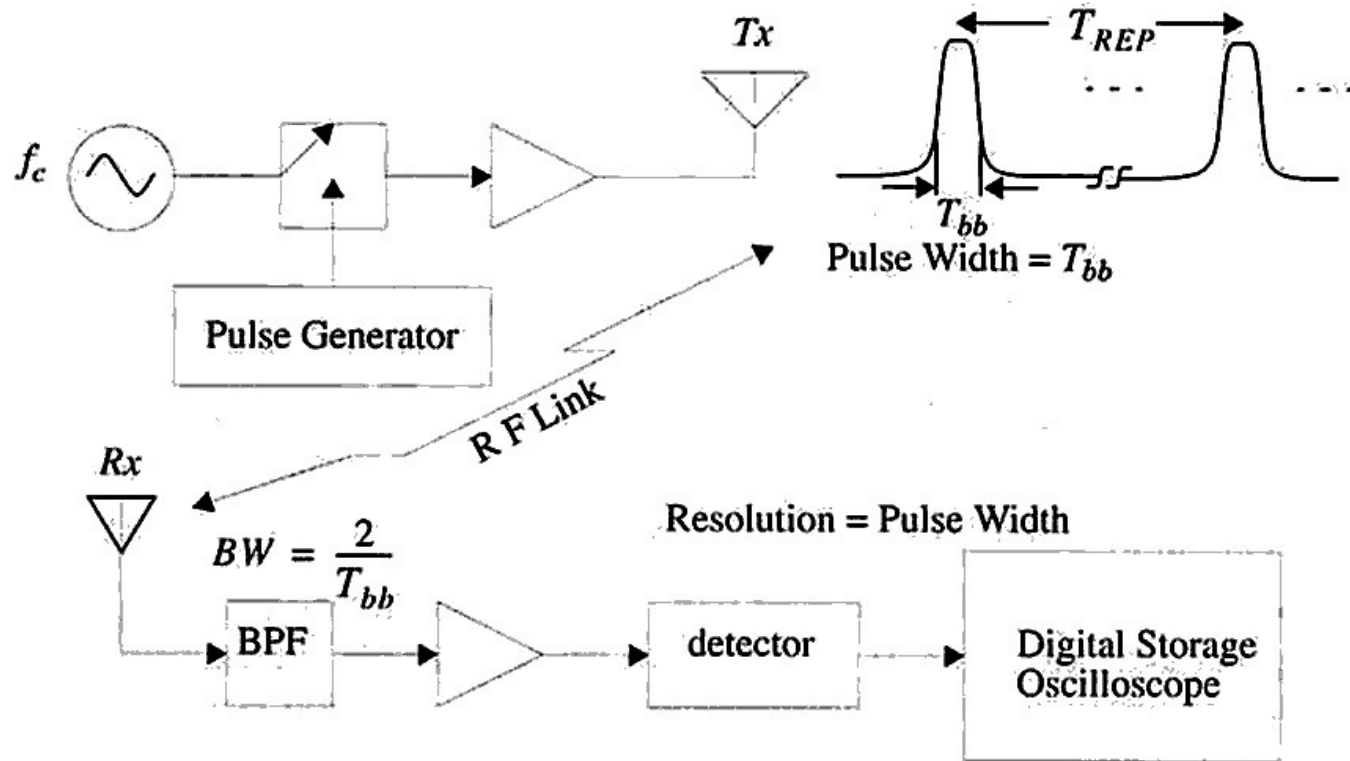
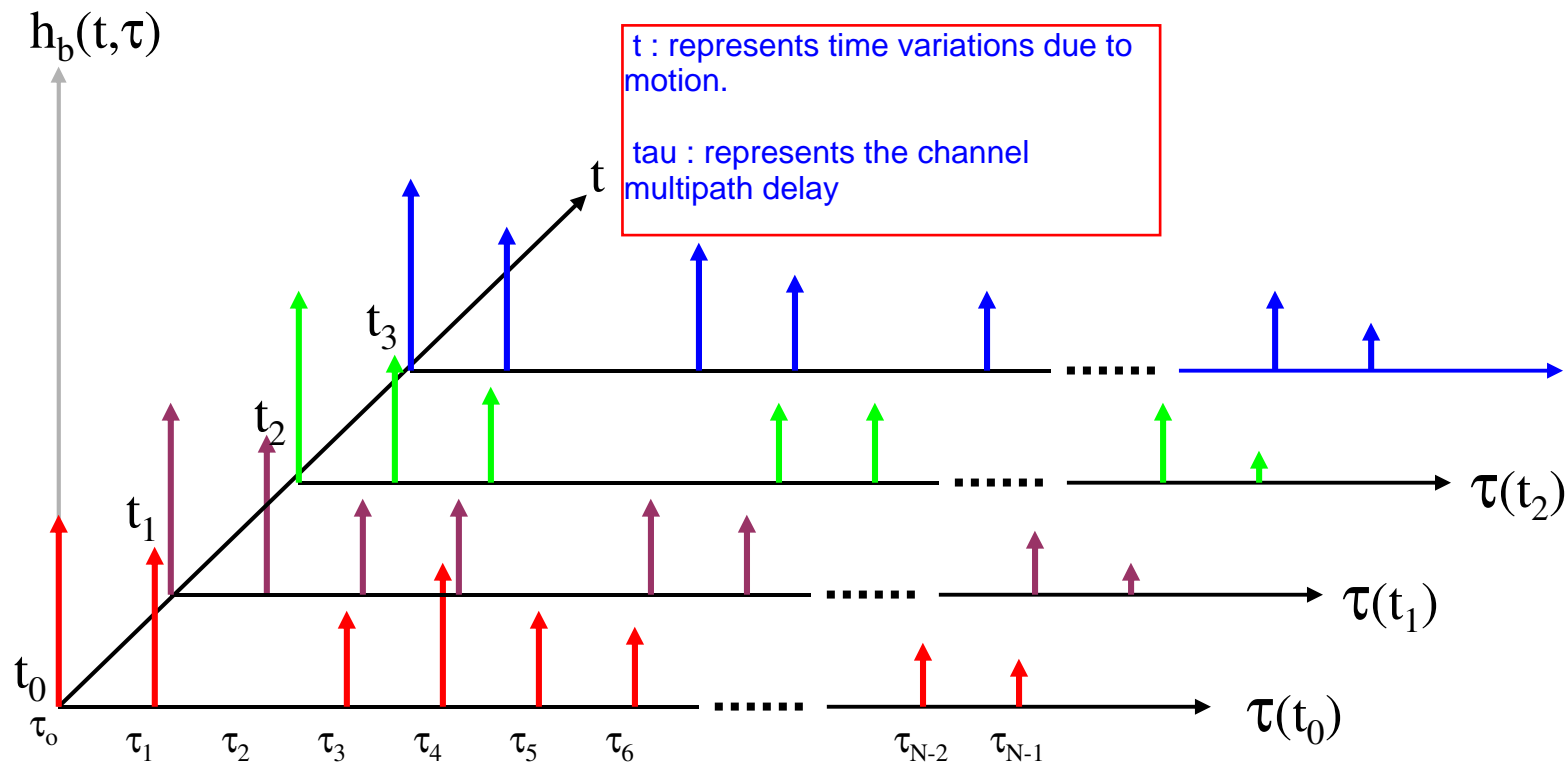


Figure 5.6 Direct RF channel impulse response measurement system.

# MRC Impulse Response

- ◆ Amplitude and delay time of multipath returns change as mobile moves → MRC is time variant



# MRC Impulse Response

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- ◆ Model multipath returns as unit impulses

$$h_b(t) = \sum_{i=0}^{N-1} a_i(t, \tau) \exp[j\theta_i(t, \tau)] \delta(\tau - \tau_i(t))$$

- $a_i \angle \theta_i =$  amplitude & phase of multipath signals ( $\delta$ )
- $N =$  # of multipath components

- ◆ FFT of IRF gives spectral characteristics of channel  
→ frequency response!



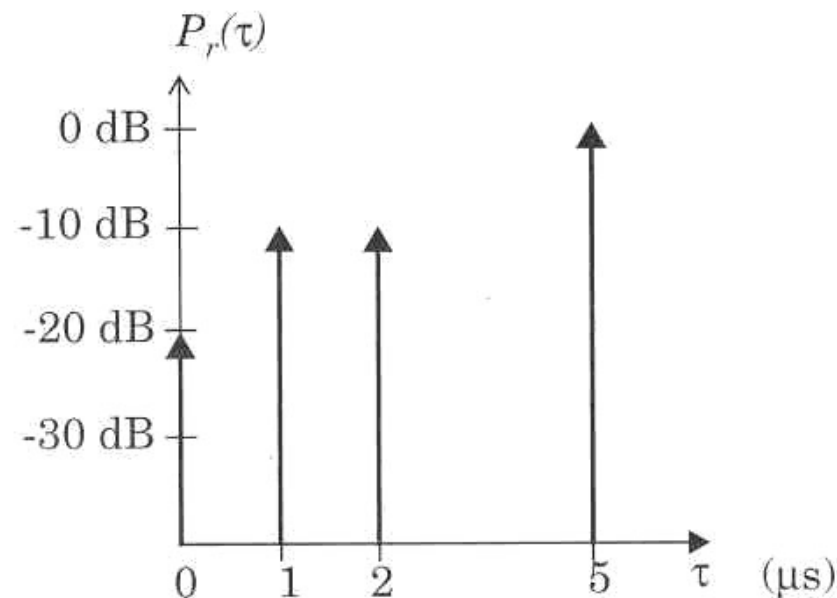
- MRC filter passband → “Channel BW” or Coherence BW  
 $= B_c$

# Multipath Channel Parameters

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## ◆ Derived from multipath power delay profiles

- $P(\tau_k)$ : relative power amplitudes of multipath signals
- Use ensemble average of many profiles in small localized area → typically 2–6 m → obtain average small-scale response



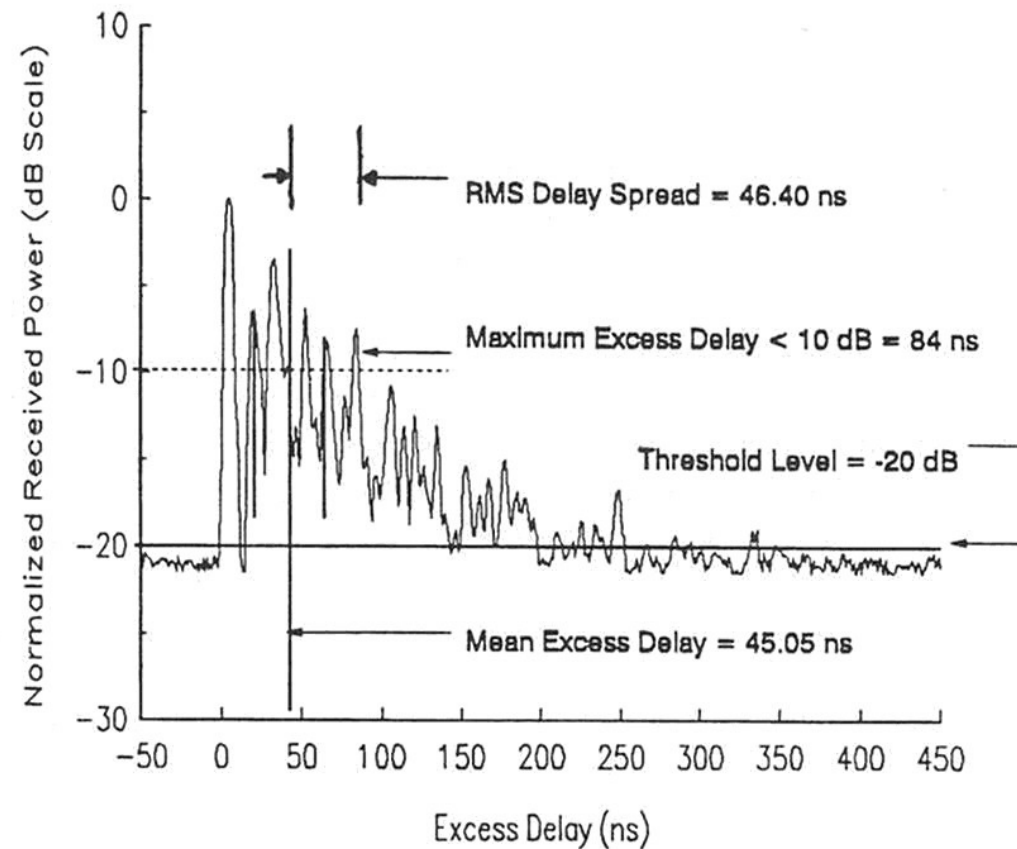


# Multipath Channel Parameters

## ◆ Time Dispersion Parameters

- Mean excess delay  $\rightarrow \bar{\tau} = \frac{\sum_k a_k^2 \tau_k}{\sum_k a_k^2} = \frac{\sum_k P(\tau_k) \tau_k}{\sum_k P(\tau_k)}$
- **RMS delay spread**  $\rightarrow \sigma_\tau = \sqrt{\overline{\tau^2} - (\bar{\tau})^2}$  and  $\overline{\tau^2} = \frac{\sum_k P(\tau_k) \tau_k^2}{\sum_k P(\tau_k)}$ 
  - » Typical values:
    - Outdoor channel ~ 2–5 μsec
    - Indoor channel ~ 20–100 nsec
- Maximum excess delay ( $X$  dB): excess delay value during which multipath power levels fall  $X$  dB **below** the maximum power level
  - » Worst case delay value
- “Excess delay” : all values computed **relative** to time of first signal arrival  $t_o$  (see figure on slide #10)

# Time Dispersion Parameters



**Figure 5.10** Example of an indoor power delay profile; rms delay spread, mean excess delay, maximum excess delay (10 dB), and threshold level are shown.

# Time Dispersion Parameters

**Table 5.1** Typical Measured Values of RMS Delay Spread

Environment	Frequency (MHz)	RMS Delay Spread ( $\sigma_\tau$ )	Notes	Reference
Urban	910	1300 ns avg. 600 ns st. dev. 3500 ns max.	New York City	[Cox75]
Urban	892	10–25 $\mu$ s	Worst case San Francisco	[Rap90]
Suburban	910	200–310 ns	Averaged typical case	[Cox72]
Suburban	910	1960–2110 ns	Averaged extreme case	[Cox72]
Indoor	1500	10–50 ns 25 ns median	Office building	[Sal87]
Indoor	850	270 ns max.	Office building	[Dev90a]
Indoor	1900	70–94 ns avg. 1470 ns max.	Three San Francisco buildings	[Sei92a]

# MRC Parameters

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- ◆ How do we characterize a time-varying MRC?
  - Statistical analyses must be used
- ◆ Four Key Characteristics of a Mobile Radio Channel (MRC)
  - Time Dispersion Characteristics
    - 1) RMS Multipath Delay Spread ( $\sigma_\tau$ )
    - 2) Coherence BW or Channel BW ( $B_c$ )
  - Frequency Dispersion Characteristics
    - 3) Doppler Spread ( $B_D$ )
    - 4) Coherent Time ( $T_c$ )

# MRC Parameters

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## ◆ RMS Delay Spread ( $\sigma_\tau$ )

- Calculated from multipath power delay profiles
- Mean Excess Delay → average delay beyond first return weighted by return power
- RMS Delay Spread → 1 standard deviation (SD) of delay values about the mean excess delay
- Statistical measures of propagation delay of interfering signals
  - » Desire small  $\sigma_\tau$
  - » Typical values:
    - outdoor channel ~ 1–5  $\mu\text{sec}$
    - indoor channel ~ 20–100 nsec

# MRC Parameters

RMS Delay Spread

$$\sigma_{\tau} = \sqrt{\overline{\tau^2} - (\overline{\tau})^2}$$

Mean Excess Delay

$$\overline{\tau} = \frac{\sum_k P(\tau_k) \tau_k}{\sum_k P(\tau_k)}$$

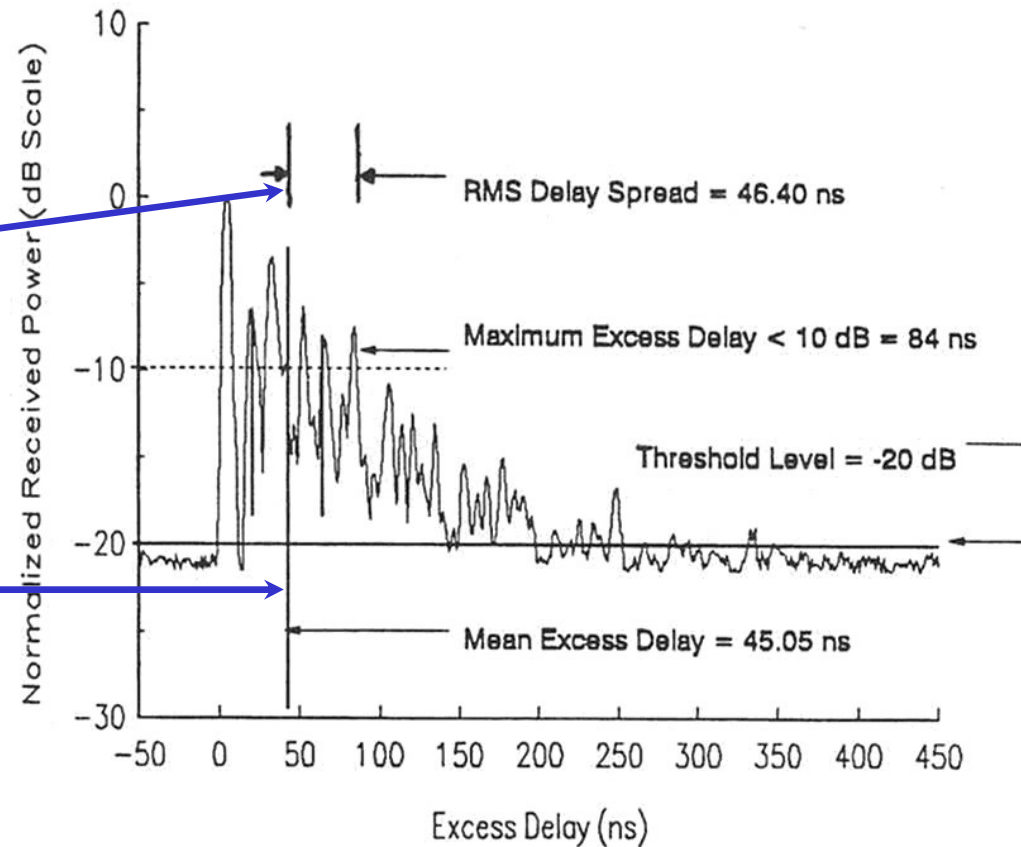


Figure 5.10 Example of an indoor power delay profile; rms delay spread, mean excess delay, maximum excess delay (10 dB), and threshold level are shown.

# MRC Parameters

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- ◆ Coherence BW or Channel BW ( $B_c$ )
  - Directly related to RMS Delay Spread
  - FFT of multipath delay profile shows frequency (spectral) characteristics of MRC
  - $B_c$  : statistical measure of frequency range where MRC response is **flat**
    - » “Flat” = passes all frequencies with  $\approx$  equal gain & linear phase
    - » Amplitudes of different frequency components correlated
      - 0.5 correlation  $\rightarrow B_c \approx 1 / 5 \sigma_\tau$
      - 0.9 correlation  $\rightarrow B_c \approx 1 / 50 \sigma_\tau$  (worst case/conservative)

# MRC Parameters

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## ◆ Coherence BW or Channel BW ( $B_c$ )

- FFT of multipath delay (channel IRF) gives frequency characteristics of channel
- MRC filter passband  $\rightarrow$  Channel or Coherence BW =  $B_c$



- \*\*\*MRC has bandlimited BPF response  $\rightarrow$  multipath signals are the direct cause\*\*\*
- MRC is fundamentally a bandlimited channel
  - » Tx signals with BW  $> B_c$  will be distorted in frequency and time domain!!



# MRC Parameters

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## ◆ Coherence BW or Channel BW ( $B_c$ )

- $B_c$  and  $\sigma_\tau$  are **related** quantities that characterize time-dispersive nature of MRC from multipath interference
  - » Frequency vs. Time domain perspective for **same** phenomena
- $B_c$  and  $\sigma_\tau$  do **NOT** characterize time-varying nature of MRC due to motion of mobile and/or surrounding objects

# MRC Parameters

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- ◆ Doppler Spread ( $B_D$ ) : measure of spectral broadening of Tx signal caused by motion → i.e. Doppler shift
  - $B_D = \text{max Doppler shift} = f_{max} = v_{max} / \lambda$  ( $\sim B_D = 50\text{-}200$  Hz)
  - If Tx signal  $B_s \gg B_D$  then frequency effects of Doppler spread are **NOT** important
  - Important for low bps (data rate) applications (e.g. paging)
- ◆ Coherence Time ( $T_c$ )
  - $T_c$  : statistical measure of time interval over which MRC remains invariant → amplitude & phase of multipath signals  $\approx$  constant
  - For digital communications →  $T_c = 0.423 / B_D$
  - Provides physical measure of how fast the channel conditions change
    - »  $T > T_c$  → changing channel → signal fluctuation/fading

# Small Scale Fading

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## ◆ Types of Small-Scale Fading

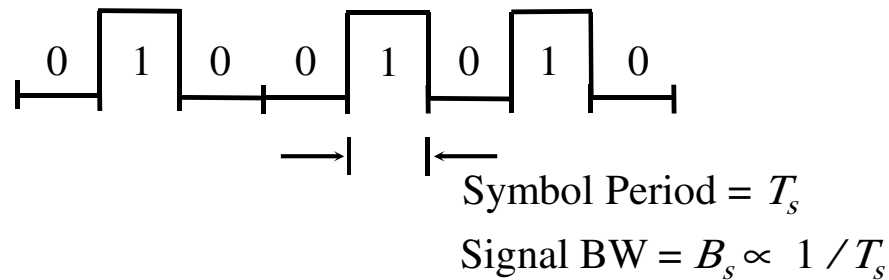
Fading can be caused by two independent MRC propagation mechanisms:

- 1) Time dispersion → multipath delay ( $B_c, \sigma_\tau$ )
- 2) Frequency dispersion → Doppler spread ( $B_D, T_c$ )

# Small Scale Fading

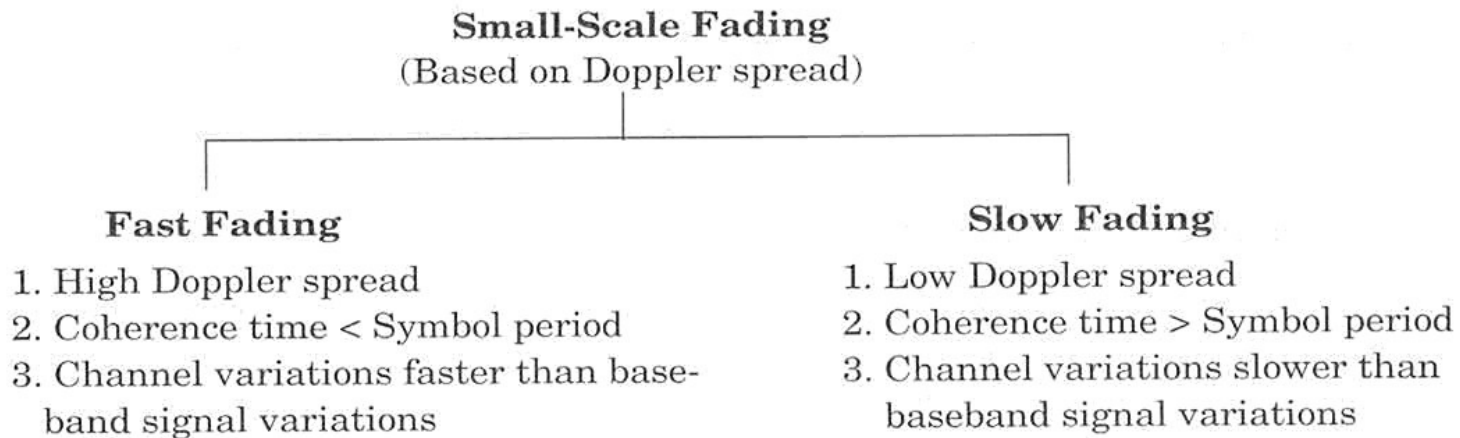
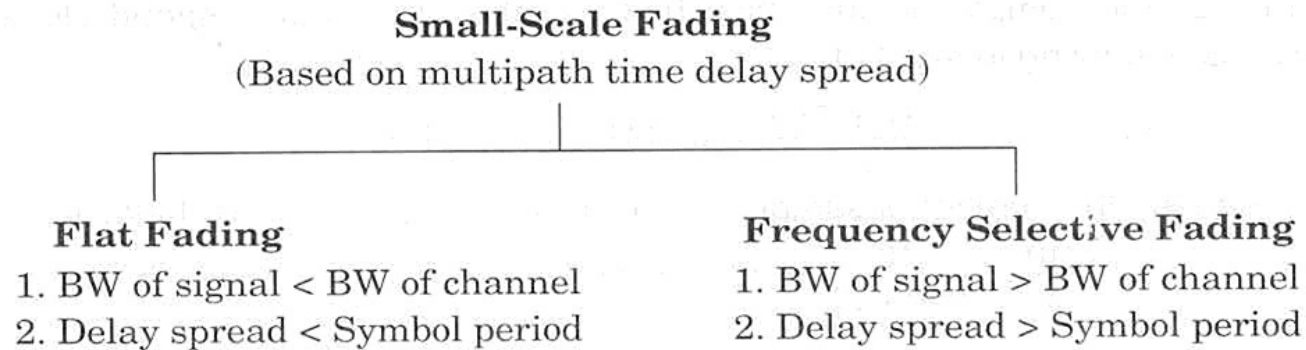
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- ◆ Relationship between Tx signal parameters and channel parameters lead to **four** distinct effects
- ◆ Important **digital** Tx signal parameters → symbol period & signal BW



# Small Scale Fading

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# Fading Types

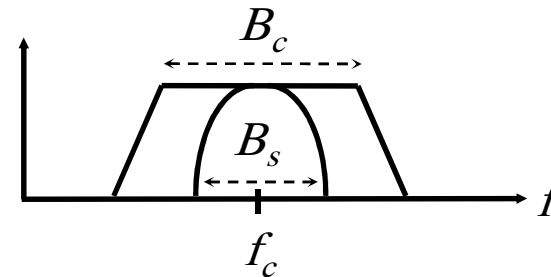
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## 1) Fading due to Multipath Delay

A) Flat Fading  $\rightarrow B_s \ll B_c$  or  $T_s \gg \sigma_\tau$

- Signal BW  $\ll$  Channel BW

- » Frequency domain perspective
- » Common type of fading
- » Spectral properties of Tx signal preserved
- » Channel “gain” varies with time causing deep fades
- » Fades  $\sim$  20–30 dB  $\rightarrow$  Rayleigh fading



# Fading Types

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## 1) Fading due to Multipath Delay

### A) Flat Fading (continued) $T_s \gg \sigma_\tau$ ???

- Symbol Period  $\gg$  RMS Delay Spread

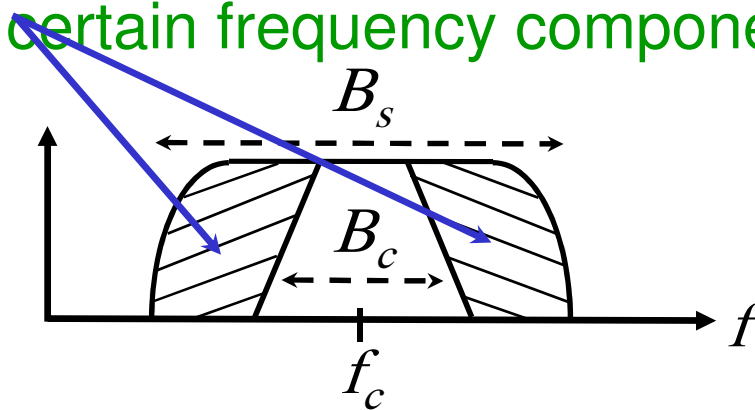
- » All multipath signals arrive at mobile Rx within  $\approx$  same symbol period
  - No Inter-Symbol Interference (ISI)
- » Interference does cause signal amplitude to vary from symbol to symbol
- » Generally considered desirable!
  - Forward link  $\rightarrow$  increase mobile Rx gain (AGC)
  - Reverse link  $\rightarrow$  increase mobile Tx power (power control)

# Fading Types

## 1) Fading due to Multipath Delay

B) Frequency Selective Fading  $\rightarrow B_s > B_c$  or  $T_s < \sigma_\tau$

- $B_s > B_c \rightarrow$  certain frequency components of signal attenuated



- Frequency distortion causes time domain shape of transmitted signal to be distorted as well



# Fading Types

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## 1) Fading due to Multipath Delay

### B) Frequency Selective Fading (continued)

- $T_s < \sigma_\tau$  ??? → **delayed** versions of Tx signal arrive during **different** symbol periods
  - » e.g. LOS → “1” & multipath “0” (from prior symbol!)
  - » InterSymbol Interference → ISI
  - » **Very** undesirable → must compensate by “equalizing” Rx signal spectrum by providing more gain @ certain frequencies
- Very difficult to predict mobile Rx performance

# Fading Types

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## 2) Fading due to Doppler Spread

A) Fast Fading  $\rightarrow T_s > T_c$  or  $B_s < B_D$

- $T_s > T_c$ 
  - » MRC changes within 1 symbol period
  - » Rapid amplitude fluctuations
- $B_s < B_D$ 
  - » Doppler shifts significantly alter spectral BW of TX signal
  - » Signal “spreading”
- Only occurs for low data rate applications  $\rightarrow$  large  $T_s$
- Uncommon in most digital communication system fades

# Fading Types

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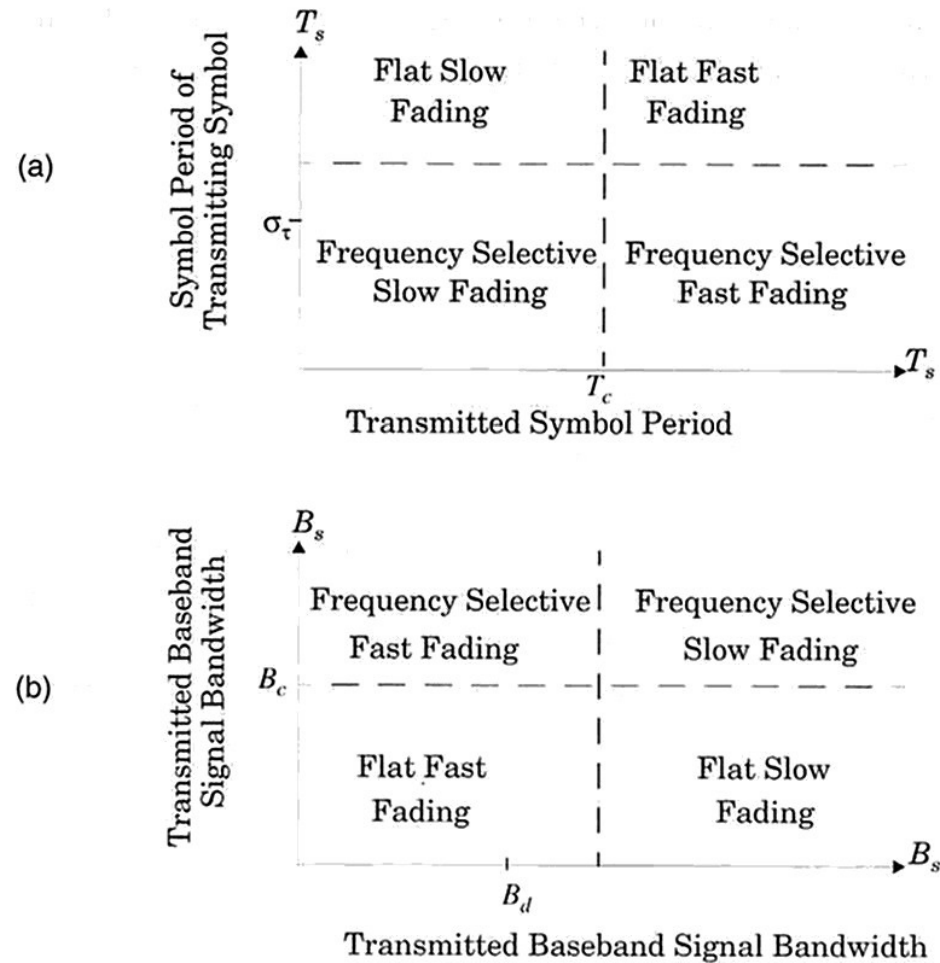
## 2) Fading due to Doppler Spread

A) Slow Fading  $\rightarrow T_s \ll T_c$  or  $B_s \gg B_D$

- MRC constant over many symbol periods
- Slow amplitude fluctuations
  - » For  $v = 60$  mph @  $f_c = 2$  GHz  $\rightarrow B_D = 178$  Hz
  - »  $B_s \approx 2$  kHz  $\gg B_D$
- $B_s$  almost always  $\gg B_D$  for most applications

# Fading Types

Flat/Slow Fading  
is most desirable



# Fading Signal Distributions

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- ◆ Small-scale fading often referred to as “Rayleigh fading”
  - Random amplitude fluctuations follow a Rayleigh PDF
  - Applies for flat fading channel only
  - Rayleigh PDF

$$p(r) = \begin{cases} \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) & 0 \leq r \leq \infty \\ 0 & r < 0 \end{cases}$$

- »  $\sigma$ : RMS value of Rx signal before detection (demodulation)
- » Common model for Rx signal variation
  - Urban areas → heavy clutter → no LOS path

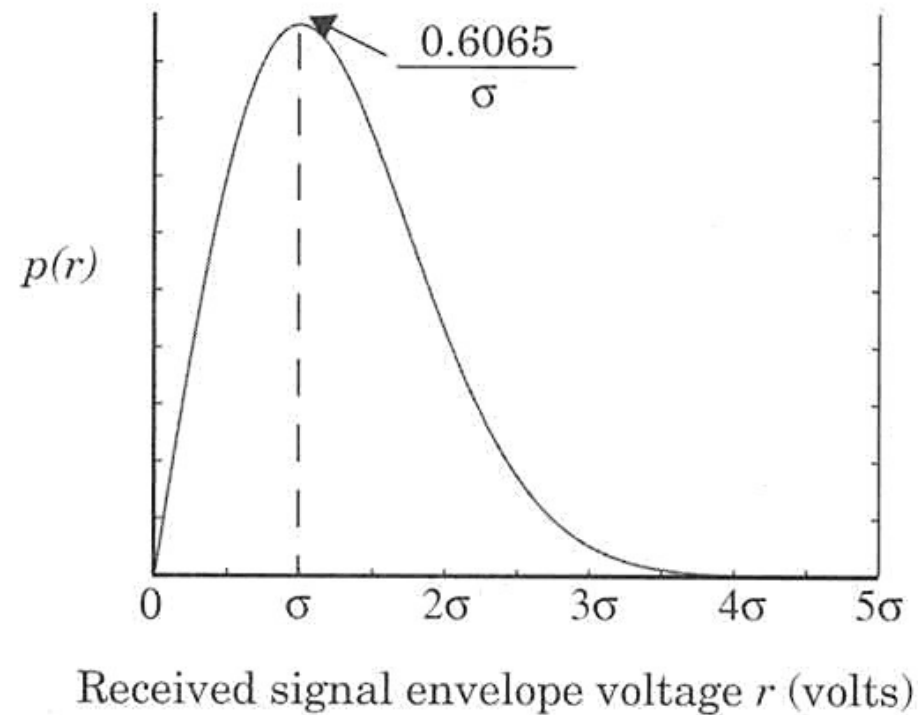
# Raleigh PDF

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$$p(r) = \begin{cases} \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) & 0 \leq r \leq \infty \\ 0 & r < 0 \end{cases}$$

Probability that signal exceeds predefined threshold level  $R$

$$\text{Prob}(r > R) = \int_R^{\infty} p(r) dr = \exp\left(\frac{-R^2}{2\sigma^2}\right)$$



# Fading Signal Distributions

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## ◆ Ricean PDF

- One dominant signal component along with weaker multipath signals
- Dominant signal → LOS path
  - » Suburban or rural areas with light clutter

$$p(r) = \begin{cases} \frac{r}{\sigma^2} \exp\left(-\frac{(r^2 + A^2)}{2\sigma^2}\right) I_0\left(\frac{Ar}{\sigma^2}\right) & A \geq 0, r \geq 0 \\ 0 & r < 0 \end{cases}$$

**A:** Peak amplitude of dominant signal  
 **$I_0$ :** Modified Bessel function

# Ricean PDF

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$$K = 10 \log \left( \frac{A^2}{2\sigma^2} \right) \text{ dB}$$

For  $A \rightarrow 0$  then  $K \rightarrow -\infty$

Ricean PDF  $\rightarrow$  Rayleigh PDF

