

## Convolution Sum Representation Of LTI Systems: (Proof): V.V.V Imp

The response of a linear system to a discrete time signal  $x[n]$  is the superposition of the scaled responses of the system to each of the shifted impulses.

Consider the response of a linear system to an arbitrary input  $x[n]$ . Let  $h_k[n]$  denote the response of the linear system to the shifted unit impulse  $\delta[n-k]$ . Then according to the superposition property for a linear system, the response  $y[n]$  of a linear system to the input  $x[n]$  is simply the weighted linear combination of these basic responses.

i.e

$$y[n] = \sum_{k=-\infty}^{+\infty} x[k] h_k[n] \quad \longrightarrow (1)$$

Let a signal  $x[n]$  is applied as the input to a linear system whose responses are given by:

If the linear system is also time invariant, these responses to time-shifted unit impulses are all time shifted versions of each other. Since,  $\delta[n-k]$  is a time-shifted version of  $\delta[n]$ , the response  $h_k[n]$  is a time-shifted version of  $h_0[n]$  i.e.

$$h_k[n] = h_0[n-k]$$

For notational convenience;  $h[n] = h_0[n]$ .

Hence, for an LTI system, eq (1) becomes:

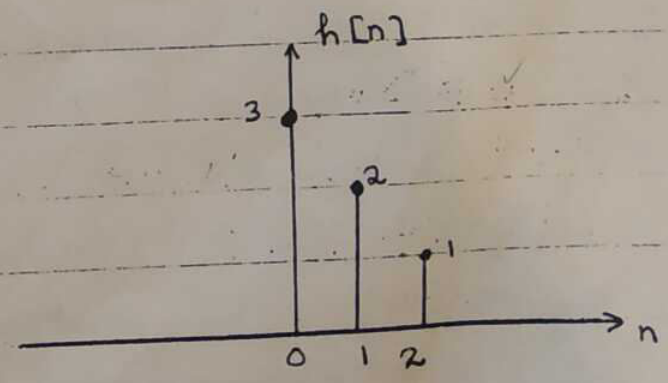
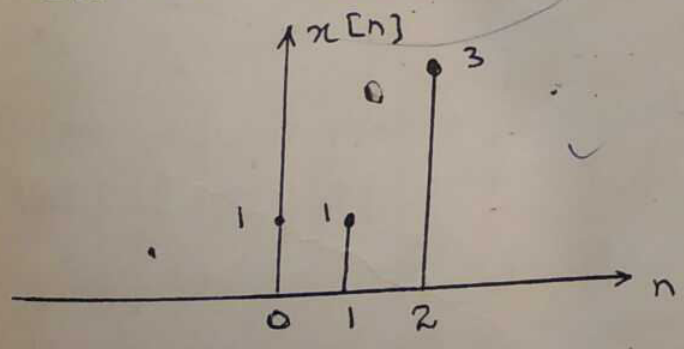
$$y[n] = \sum_{k=-\infty}^{+\infty} x[k] h[n-k]$$

This result is known as the convolution sum or superposition sum & the operation on the right hand side is known as the convolution of the sequences  $x[n]$  and  $h[n]$ . This can also be represented as:

$$y[n] = x[n] * h[n]$$

Example:

Given that:



Find  $y[n]$  using Convolution Summation.

Solution:

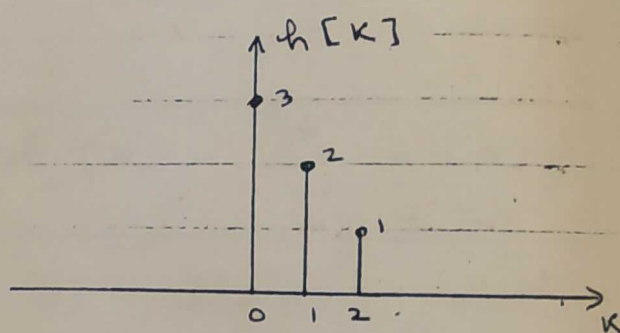
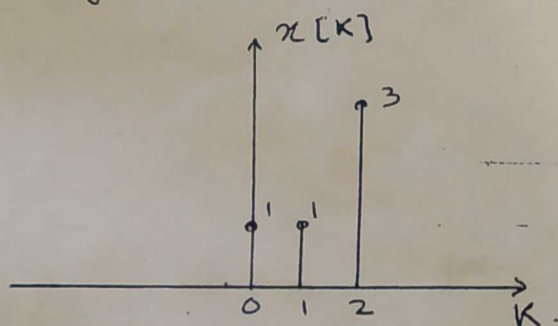
As we know that the formula for convolution summation is given by,

$$y[n] = x[n] * h[n]$$

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

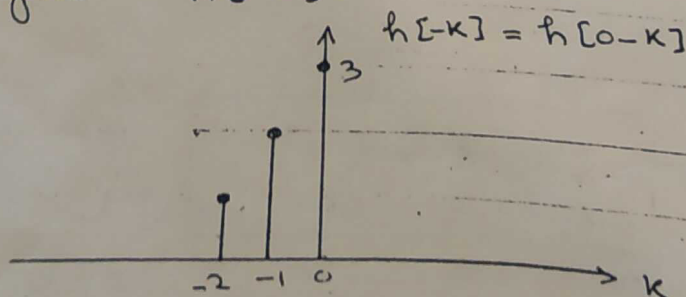
Step #1:

Replace "k" for "n" in the given signal & impulse response.



Step #2:

Reflect the signal (i.e. impulse response)  $h[k]$  to get  $h[-k]$ .



Step #3:

For the interval.

$$-\infty < n < 0$$

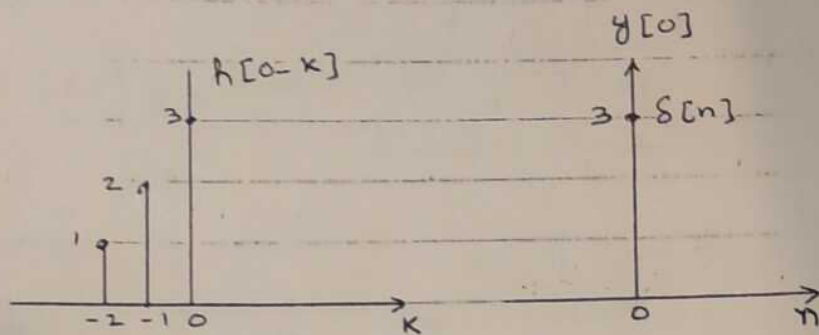
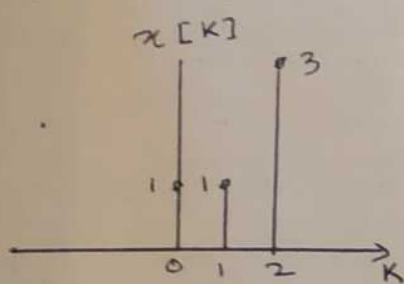
$h(n-k)$  is a value between  $-\infty$  and 0. So when  $h(n-k)$  is multiplied by  $x[k]$ , the output is zero. i.e.

$$y[n] = 0$$



For  $n \geq 0$ .

At  $n=0$  :-



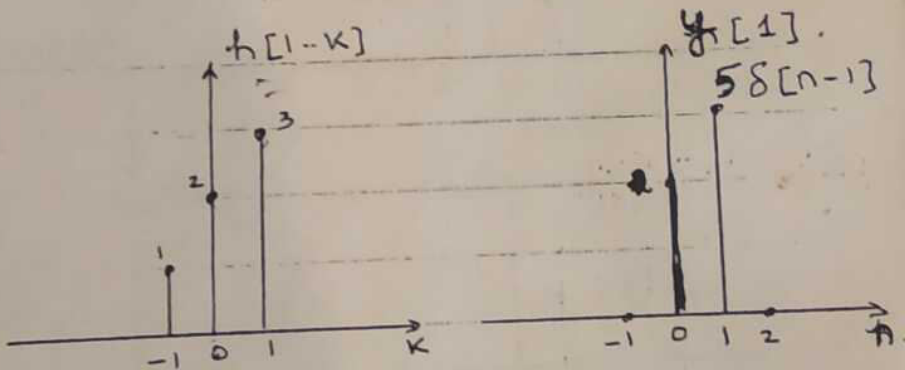
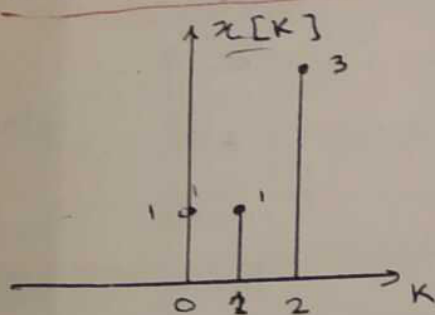
i.e

$$y[0] = \sum_{k=-\infty}^{\infty} x[k] h[0-k]$$

$$= (1)(1) + (1)(2) + (3)(3)$$

$$\boxed{y[0] = 3} \Rightarrow y[0] = 3 \delta[n] \rightarrow (1)$$

At  $n=1$



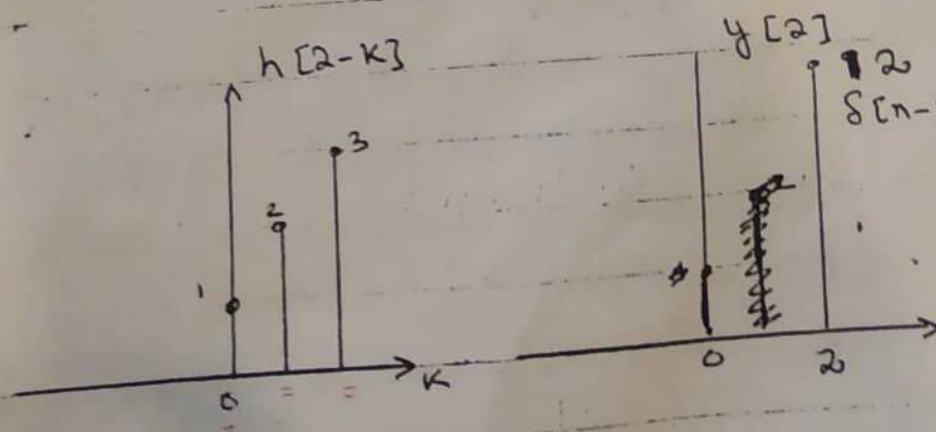
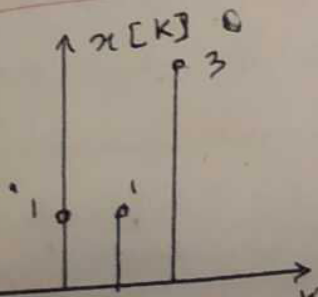
i.e

$$y[1] = \sum_{k=-\infty}^{\infty} x[k] h[1-k]$$

$$= (2)(1) + (1)(2) + (3)(3)$$

$$\boxed{y[1] = 5} \Rightarrow y[1] = \text{[scribble]} + 5 \delta[n-1] \rightarrow$$

At  $n=2$  :-

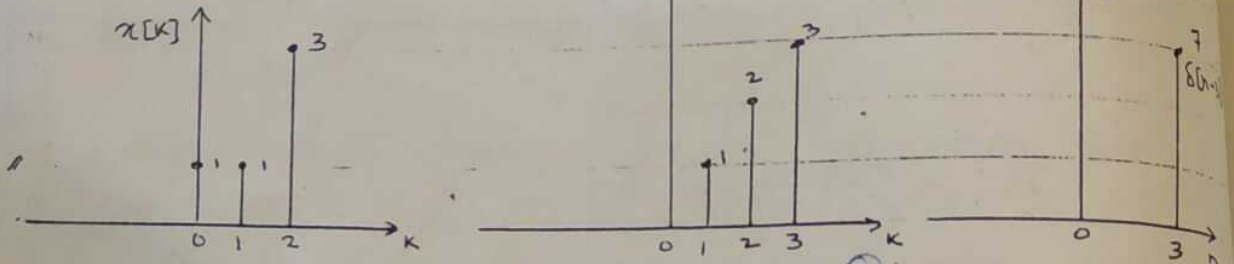


$$y[2] = \sum_{k=0}^{\infty} x[k] h[2-k]$$

$$y[2] = 1 + 2 + 9$$

$$\boxed{y[2] = 12} \Rightarrow y[2] = 12 \delta[n-2]$$

At  $n=3$ :

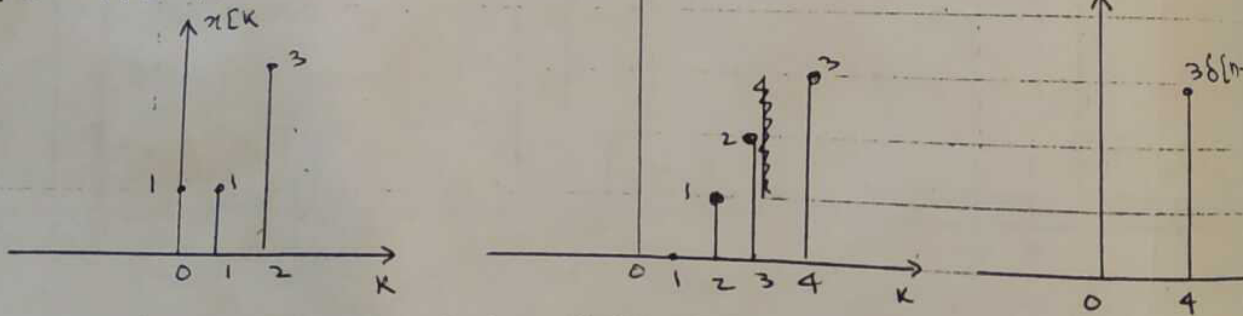


i.e.  $0 \times 1 + 1 \times 1 + 2 \times 3 + 3 \times 0 = 6 + 1 = 7$

$$y[3] = (1)(1) + (3)(2) = 7$$

$$= 7 \delta[n-3]$$

At  $n=4$ :



$$y[4] = 3 \delta[n-4] \quad (1 \times 0 + 1 \times 0 + 3 \times 1 +$$

For  $n > 4$

There is no overlapping of the signal  $x[k]$  &  $h[n-k]$ . Hence.

$$y[n] = 0$$

Overall output  $y[n]$

Overall output  $y[n]$  can be written

as:

$$\boxed{y[n] = 3 \delta[n] + 5 \delta[n-1] + 12 \delta[n-2] + 7 \delta[n-3] + 3 \delta[n-4]}$$

graphically:

