

Name : Muhammad Saqib Khalil

ID : 13342

Subject : Power Electronics

Program : BE (Electrical)

Semester : 8th

Date : 27/06/2020

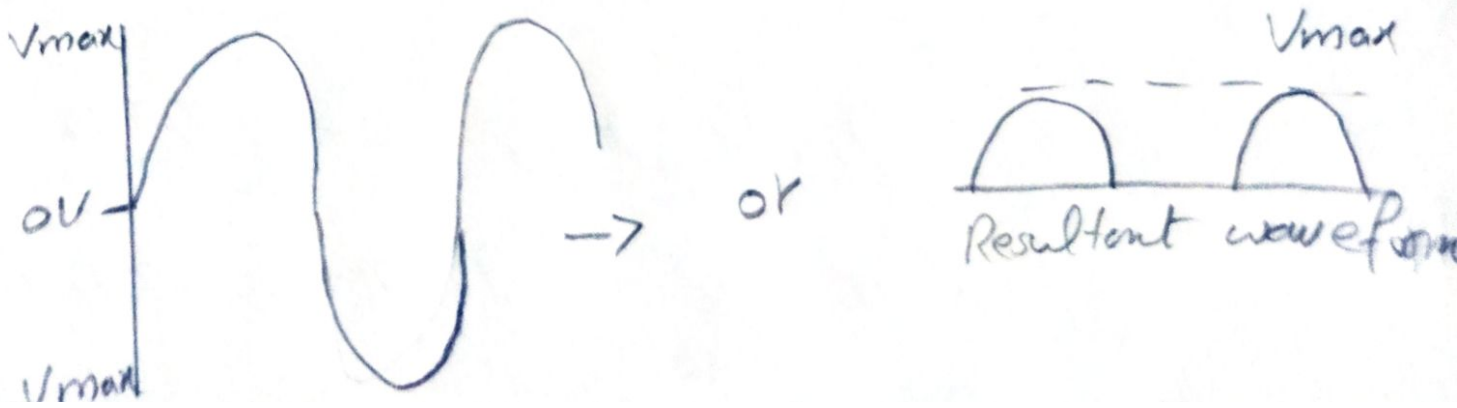
Submitted to : Engr. SHAYAN TARIQ JAN

Q#01

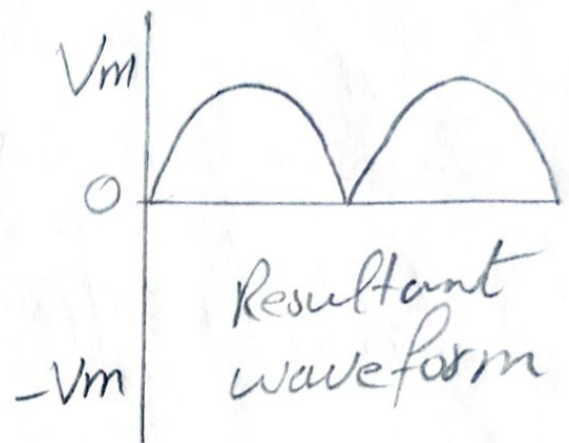
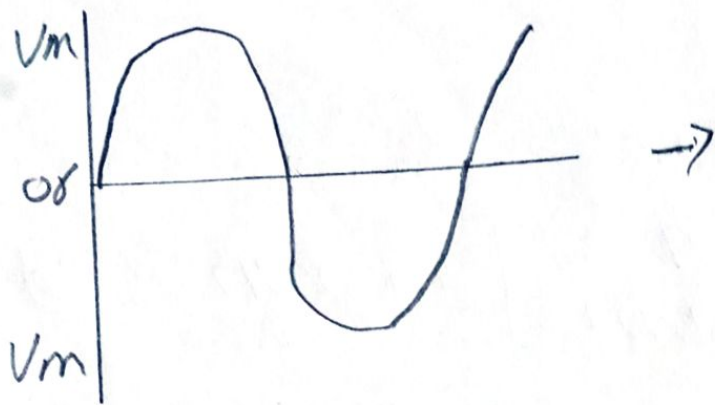
①

Difference between single phase half wave and full wave bridge rectifier:

- ① Half wave rectifier which convert only one half of the AC cycle into pulsating DC ~~current~~ while full wave rectifier is an electronic circuit which convert entire cycle AC into pulsating DC
- ② Half wave utilize only half of AC cycle for the conversion while full wave utilize full wave of AC cycle
- ③ Half wave is unidirectional, the conduction is one direction only either convert positive or negative, that why called Half wave rectifier is bidirectional, it convert for positive as well as negative half of the cycle
- 4) output waveform of single phase half wave rectifier



and single phase wave bridge rectifier ②



- 5) The number of diode in half wave rectifier is 1 while in bridge rectifier is 4.

Similarities between single phase Half wave & full wave bridge rectifier:-

- 1) Peak inverse voltage of single half wave and full wave rectifier are same which is V_m & same in both rectifier
- ② Both utilize the single phase for the operation.

③

(2) single phase uncontrol and control rectifier difference & similarities:-

① uncontrol they are naturally turn on whenever a positive voltage is applied between its terminal & when you stop by applying it negative voltage

while in control rectifier, the conduction start at any angle in positive half cycle normally 0 to 180 degree once the conduction start can be turn on and OFF

④

Q#02

Given:

$$V_m = 42V$$

$$R = 13\Omega$$

Sol:

For half wave

1) V_{dc} :

$$\frac{V_m}{\pi}$$

where $V_m = 42V$ & $\pi = 3.14$

putting these values in eq ①

$$V_{dc} = \frac{42}{3.14}$$

$$V_{dc} = 13.37V$$

For full wave bridge

$$\frac{2V_m}{\pi}$$

putting value

$$V_{dc} = \frac{2(42)}{3.14}$$

$$V_{dc} = 26.75V$$

(2) I_{dc} :

(5)

For half wave

$$I_{dc} = \frac{V_m}{\pi R}$$

$$I_{dc} = \frac{42}{(3.14)13}$$

$$I_{dc} = \frac{42}{40.82}$$
$$= 1.028 \text{ Amp}$$

For full wave

$$I_{dc} = \frac{I_m}{\pi} \text{ --- (2) where } I_m = \frac{V_m}{R}$$

$$I_m = \frac{42}{13}$$

$$I_m = 3.23 \text{ Amp}$$

put it in eq (2)

$$I_{dc} = \frac{3.23}{3.14}$$

$$I_{dc} = 1.0286 \text{ Amp}$$

(3) V_{rms} :

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For half wave:

$$V_{rms} = \frac{V_m}{2}$$

$$= \frac{42}{2}$$

$$V_{rms} = 21 \text{ V}$$

For full wave

$$V_{rms} = \sqrt{2} V_s$$

$$V_{rms} = \sqrt{2} V_s \text{ --- } \textcircled{3}$$

$$\text{As } V_s = \frac{V_m}{\sqrt{2}}$$

$$= \frac{42}{\sqrt{2}}$$

$$= \frac{42}{1.414}$$

$$V_s = 29.70$$

putting value of V_s in eq $\textcircled{3}$

$$V_{rms} = (\sqrt{2})(29.70)$$

$$= (1.414)(29.70)$$

$$\boxed{V_{rms} = 42.99 \text{ V}}$$

4) I_{rms} : (For half wave & full wave)

For half wave

$$\begin{aligned} I_{rms} &= \frac{V_m}{2R} \\ &= \frac{42}{2(13)} \\ &= \frac{42}{26} \end{aligned}$$

$$I_{rms} = 1.61 \text{ Amp}$$

For full wave:

$$I_{rms} = \frac{I_m}{2} \quad \text{--- eq (1)}$$

$$\begin{aligned} \text{where } I_m &= \frac{V_m}{R} \\ &= \frac{42}{13} \end{aligned}$$

$$I_m = 3.23 \text{ A}$$

put value of I_m in eq (1)

$$I_{rms} = \frac{3.23}{2}$$

$$I_{rms} = 1.615 \text{ A}$$

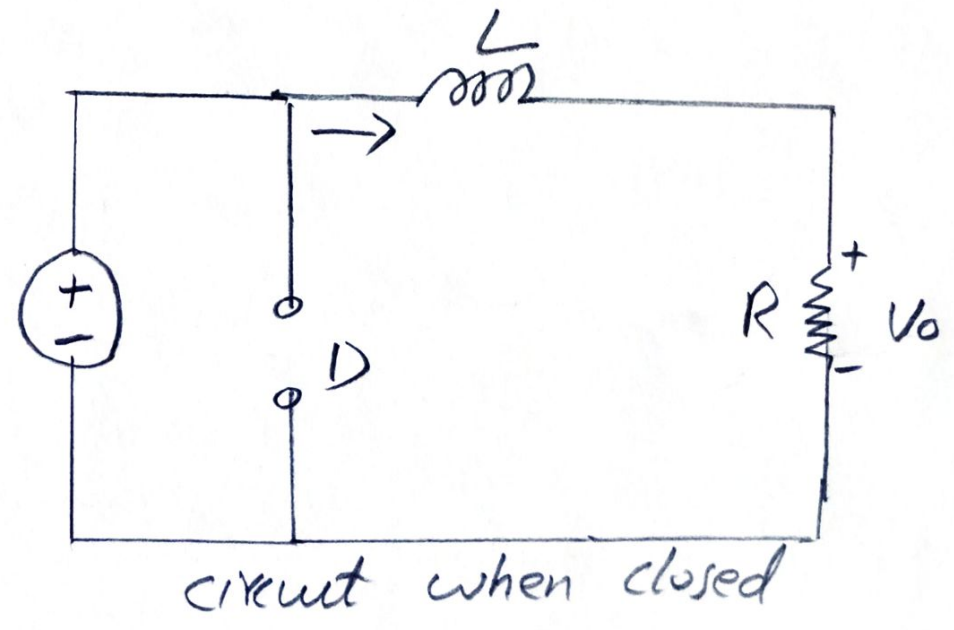
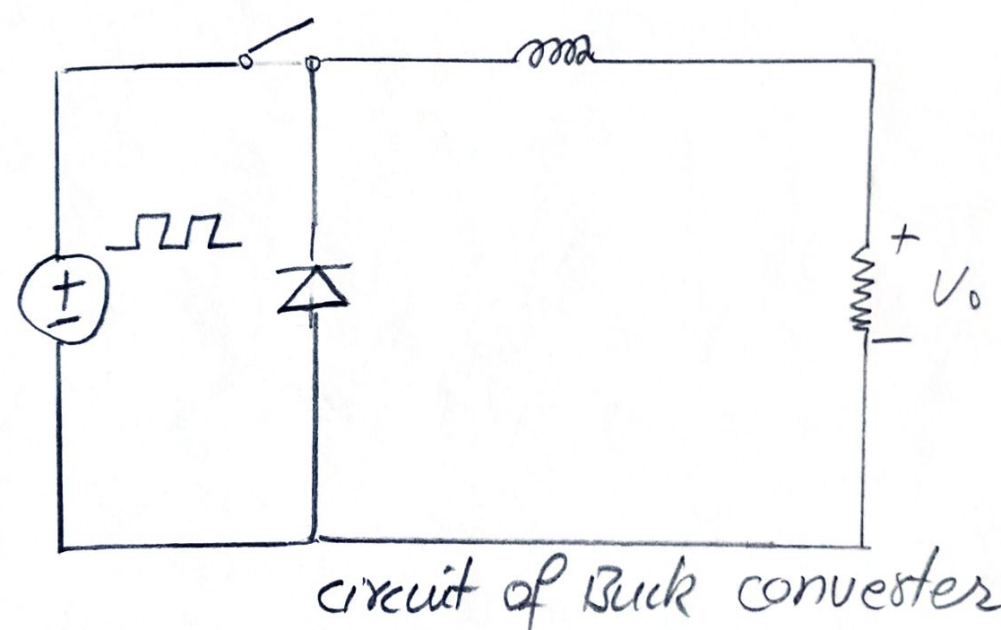
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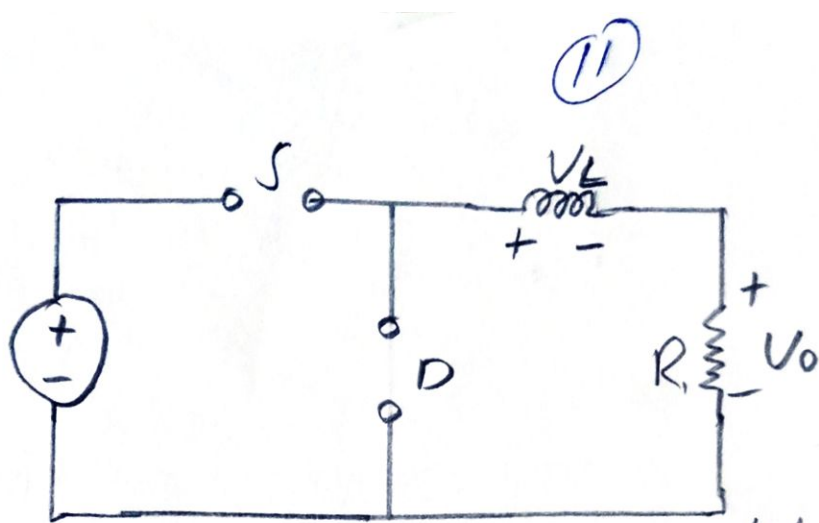
I would like to refer the uncontrol full wave bridge rectifier because the efficiency of the full wave bridge rectifier is better than in half wave rectifier and output frequency also greater than half wave rectifier.

Buck chopper:

- 1) Output voltage is less than input voltage
- 2) The thyristor in the circuit acts as a switch
- 3) When thyristor is ON, supply voltage appears across the load
- 4) When thyristor is OFF, the voltage across the load will be zero
- 5) Practical arrangement includes an inductor L and diode which are used to eliminate current pulsation providing a smooth DC current
- 6) With S closed, D is off and it remains off and it remains off as long as S is ON
- 7) The i_p current builds up exponentially and flows through L & Load
- 8) V_o equal to V_i
- 9) With S off or open, the current through I decays to zero
- 10) This causes inductive voltage with opposite polarity across L .

- 11) V_2 forward bias diode D
- 12) current flows through L & Load & Diode D
- 13) This arrangement permit the use of simple filter inductance L to provide a satisfactorily smooth DC Load current
- 14) with high switch frequency, smaller inductance is sufficient to get desired output.





circuit when switch is open

Given data:

$$V_{in} = 50V$$

$$D = 42\%$$

$$R = 13\Omega$$

$$\text{Frequency } (f) = 20\text{kHz}$$

1) V_{out}

we know that

$$V_{out} = \alpha V_s \text{ OR } D \times V_s \quad \text{--- (1)}$$

Here $\alpha =$ Duty cycle

$$\text{which } 42\% = 0.42$$

putting all value in eq (1)

$$V_{out} = (0.42)(50)$$

$$\boxed{V_{out} = 21V}$$

(2) I_{out}

(12)

$$I_{out} = \frac{V_o}{R}$$
$$= \frac{21}{13}$$

$$I_{out} = 1.615 \text{ A}$$

3) I_{in} :-

we know that

$$I_o = \frac{I_i}{d \cdot D}$$

$$I_i = I_o \times D$$

$$I_i = 1.615 \times 0.42$$

$$I_i = 0.6783$$

(4) Inductor:

we know that

$$L = \frac{T_{off} \times R}{2}$$

Let's suppose $T_{off} = 0.009$

$$L = \frac{0.009}{2} \times 13$$

$$L = 0.0585 \text{ H}$$

Boost chopper:-

- ① The output voltage is more than the input voltage by several times
- ② L is used to provide smooth input current
- ③ The SCR(s) acts as the switch which work in PWM mode
- ④ with S ON, the L is connected to the supply
- ⑤ Load voltage V_L jumps instantaneously to V_i but current through L increase linearly & stored energy
- ⑥ when S is open, the current collapses & ~~error~~ energy stored in L is transferred to C through D
- ⑦ The induced voltage across the inductor reverse and adds to source voltage, Voltage increasing output voltage
- ⑧ The current that was flowing through S now flow through L , D & C to load.
- ⑨ Energy stored in inductor is released to load
- ⑩ when S closed again, D become reverse biased, the capacitor energy supplied the load voltage & cycle again

$$V_o = V_i + V_L$$

- (11) V_o is always higher than V_i as polarity of inductor voltage V_L is same as V_i
- (12) If inductor L is very large, source current I_i is ripple free & considered constant $W_{on} = V_i I_i T_{on}$
- (13) Assuming C to be large enough to neglect the voltage ripple, V_o is considered constant

$$W_{off} = (V_o - V_i) * I_c * T_{off}$$

- (14) Since losses are neglect, the energy stored transferred during T_{off} by L min be equal to energy gained during T_{on} $W_{on} = W_{off} = V_i I_i T_{on} = (V_o - V_i) * I_c * T_{off}$

$$V_o = V_i \left(1 + \frac{T_{on}}{T_{off}} \right) = V_i \left(\frac{T}{T - T_{on}} \right)$$

$$V_c \left(\frac{1}{1 - \frac{T_{on}}{T}} \right) = V_c \left(\frac{1}{1-d} \right)$$

Thus V_o is always greater than V_i

$$\rightarrow P_i = P_o \rightarrow V_i I_i = \frac{V_o^2}{R} \rightarrow I_i = \frac{V_o^2}{V_i} * \frac{1}{R}$$

$$\rightarrow I_o = I_i * \frac{T_{off}}{T} \Rightarrow I_o = I_i (1-d)$$

$$\rightarrow P_o = P_i \Rightarrow V_i I_i = \frac{V_o^2}{R} = \frac{V_i^2}{(1-d)^2} * \frac{1}{R}$$

$$\rightarrow I_i = \frac{V_i}{(1-d)^2} * \frac{1}{R}$$

$$\rightarrow I_L = \frac{I_{max} + I_{min}}{2} = I_i$$

$$I_{max} + I_{min} = 2 * I_i$$

→ Voltage across L is

(15)

$$V_L = V_i = L \frac{di}{dt}$$

$$\Delta I = \frac{V_i}{L} * T_{on} \text{ or } I_{max} - I_{min} \Rightarrow \frac{V_i}{L} T_{on}$$

$$\text{Again } I_{max} + I_{min} = 2 * I_i$$

Solving

$$I_{max} = V_i \left[\frac{L}{R(1-d)^2} + \frac{T_{on}}{2L} \right]$$

$$I_{min} = V_i \left[\frac{1}{R(1-d)^2} - \frac{T_{on}}{2L} \right]$$

$$I_{p-d} = I_{max} - I_{min} = \frac{V_i T_{on}}{L}$$

For continuous current mode

$$I_{min} = V_i \left[\frac{1}{R(1-d)^2} - \frac{T_{on}}{2L} \right]$$

$$\Rightarrow \frac{1}{R(1-d)^2} = \frac{T_{on}}{2L} \Rightarrow L = \frac{RT_{on}}{2} (1-d)^2$$

Given data:

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$$V_{in} = 50V$$

$$\text{duty cycle } D = ~~20\%~~ 42\%$$

$$\text{Resistor } R = 13\Omega$$

$$\text{frequency } F = 20\text{ KHz}$$

1) V_{out}

As we know

$$V_o = V_i \left(\frac{1}{1-d} \right)$$

$$V_o = 50 \left(\frac{1}{1-0.42} \right)$$

$$V_o = 50 \left(\frac{1}{0.58} \right)$$

$$V_o = 86.20V$$

2) I_{out} :

$$I_o = I_i (1-d) \quad \text{--- (1)}$$

First finding I_{in}

3) I_{in}

$$I_i = \frac{V_i}{(1-d)^2} * \frac{1}{R}$$

$$\Rightarrow \frac{50}{(1-0.42)^2} * \frac{1}{13}$$

(17)

$$\begin{aligned}
 I_{in} &= \frac{50}{(5.8)^2} \times \frac{1}{13} \\
 &= \frac{50}{0.3364} \times \frac{1}{13} \\
 &= 148.63 \times \frac{1}{13}
 \end{aligned}$$

$$\boxed{= 11.43 \text{ A}}$$

putting this value in eq (1)

$$I_{out} = I_1 (1-d)$$

$$I_o = 11.43(1-0.42)$$

$$I_o = 11.43(0.58)$$

$$\boxed{I_o = 6.629 \text{ A}}$$

Buck-Boost chopper:-

- It combines the concept of both step-up & step-down choppers
- The output voltage is either higher or lower than input voltage
- The output voltage polarity also be reversed
- The switch is either an SCR or GTO or

IGBT

- when S is ON, D is reverse biased & I_D is zero

→ while S is OFF, the source is disconnected

→ The current through inductor does not change instantaneously and it forward biases the diode providing path for the load.

→ with S = ON (T_{ON}); $W_{ON} = V_i \times I_i \times T_{ON}$

with S = OFF (T_{OFF}); $W_{OFF} = V_i \times I_i \times T_{OFF}$

→ Ignoring losses, $W_{ON} = W_{OFF} = V_i \times I_i \times T_{ON}$

$$\Rightarrow V_i \times I_i \times T_{OFF}$$

$$\rightarrow V_o = V_i \frac{dt}{(1-d)T} = V_i \frac{d}{(1-d)}$$

$$I_L = \frac{I_{max} + I_{min}}{2} : I_1 = \overset{(14)}{I_L} d = \frac{(I_{max} + I_{min})}{2} \times d$$

The average output $P_1 = V_1 I_1 = \frac{(I_{max} + I_{min})}{2}$
 $\times dV \Rightarrow P_0 = \frac{V_0^2}{R}$

$$\rightarrow I_{max} + I_{min} = \frac{2dV_1}{R(1-d)^2} ; I_{max} - I_{min} = \frac{V_s}{L} dt$$

$$\rightarrow I_{max} = V_1 \left[\frac{1}{R(1-d)^2} + \frac{I}{2L} \right] d$$

$$- I_{min} = V_1 \left[\frac{1}{R(1-d)^2} - \frac{I}{2L} \right] d$$

For continuous current condition

$$I_{min} = 0 = V_s \left[\frac{1}{R(1-d)^2} - \frac{T}{2L} \right] d$$

$$\Rightarrow L = \frac{RTd}{2} (1-d)^2$$



Data

$$V_{in} = 50V$$

$$V_{out} = 42\%$$

$$\text{Resistor } (R) = 13\Omega$$

$$\text{Frequency } f = 20 \text{ KHz}$$

1) Duty cycle (D)

we know that

$$\frac{V_o}{V_i} = \frac{-D}{1-D}$$

$$V_o = \frac{V_i d}{(1-d)}$$

~~0.42~~

$$0.42 = 50 \cdot \frac{d}{(1-d)}$$

$$(0.42)(1-d) = d50$$

$$0.42 - 0.42d = d50$$

$$0.42 - 0.42d$$

$$0.42 = 50d + 0.42d$$

$$0.42 = 50.42d$$

(26)

$$d = \frac{0.412}{50.412}$$

$$\boxed{d = 0.00833}$$

2) I_{out}

we know that

$$I_{max} + I_{min} = \frac{2dV_i}{R(1-d)^2}$$

$$= \frac{2(0.00833)50}{13(1-0.00833)^2}$$

$$= \frac{0.833}{12.78}$$

$$I_{max} + I_{min} = 0.065A \text{ --- (1)}$$

we know that

$$I_{out} = \frac{I_{max} + I_{min}}{2}$$

putting eq (1)
value in place
of $I_{max} + I_{min}$

$$= \frac{0.065A}{2}$$

$$\boxed{= 0.0325} \text{ Amp}$$

$$3) I_i = ?$$

$$I_i = I_c d$$

$$I_i = 0.325 \times 0.00833$$

$$I_i = 2.707 \times 10^{-3}$$

(4) Induction L

$$L = \frac{RTd}{2} (2-d)^2$$

putting value where $T = \frac{1}{F}$

~~$$L = 13(0.00005) \left(\frac{1}{F} \right)^2$$~~

$$L = \frac{13(5 \times 10^{-5}) \times 0.00833 (1 - 0.00833)^2}{2}$$

$$= \frac{5.4114 \times 10^{-6} (0.99167)^2}{2}$$

$$= (2.707 \times 10^{-9}) (0.983)$$

$$L = 2.6609 \times 10^{-5} \text{ H} \quad \text{ANSWER}$$