

Department of Computer Science
Mid Term Assignment
Date: 13/04/2020
Course Details

Course Title: Radar & Satellite Communication
Instructor: DR, Naeem Ahmad Jan

Module:
Total Marks: 30

Student Details

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Q1	(a)	Find and explain Track and Search Radar Range equation	Marks 6
	(b)	Explain working principle of Satellite communications system (GPS), and difference between triangulation & Trilateration?	Marks 4
Q2	(a)	Draw and Explain Radar Block Diagram	Marks 6
	(b)	Find the escape velocity of satellite?	Marks 4
Q3	(a)	Find out the orbital speed & Time period of satellite?	Marks 6
	(b)	Explain different types of radar systems	Marks 4

(Q1).

(PART. a). Find and explain track and Search Radar equation?

(Ans). Power density from radiating antenna.

$$\frac{P_t}{4\pi R^2}$$

. P_t = Peak transmitter Power

. R = distance from radar

Power density from directive antenna

$$\frac{P_t G_t}{4\pi R^2}$$

. G_t = transmit gain

Power of reflected signal as target

$$\frac{P_t G_t \sigma}{4\pi R^2}$$

. σ = radar cross section units

Power density of reflected signal at the radar

$$\frac{P_t}{4\pi R^2} \frac{\sigma}{4\pi R^2}$$

Power of reflected signal from target and received by radar.

$$P_r = \frac{P_t G_t}{4\pi R^2} \frac{\sigma A_e}{4\pi R^2}$$

. P_r = Power received.
. A_e = Effective area.

Power density by reflected signal is

$$P_t = \left(\frac{P_t G \sigma}{4\pi R^2} \right) \times \frac{1}{4\pi R^2}$$

$$= \frac{P_t G \sigma}{(4\pi R^2)^2}$$

If effective area of antenna A_e , received Power

$$P_r = \frac{P_t G \sigma A_e}{(4\pi R^2)^2}$$

For max range R_{max} received signal

$$P_r = S_{min}$$

$$S_{min} = \frac{P_t G \sigma A_e}{(4\pi)^2 R^4_{max}}$$

$$R_{max} = \left[\frac{P_t G \sigma A_e}{(4\pi)^2 S_{min}} \right]^{\frac{1}{4}}$$

For Parabolic Antenna

$$G = \frac{4\pi A_e}{\lambda^2}$$

Hence

$$R_{\max} = \left[\frac{P_t (4\pi A_e) \sigma A_e}{(4\pi)^2 5 \text{ min}} \right]$$

$$R_{\max} = \left[\frac{P_t A_e \sigma}{4\pi \lambda^2 5 \text{ min}} \right]^{\frac{1}{4}}$$

The noise power at the receiver is given by

$$N = k B_n T_s$$

• $T_s =$ System Noise Temperature

$k =$ Boltzman Constant

$B_n =$ Noise bandwidth of receiver

\Rightarrow Signal Power reflected from target and received by radar.

$$P_r = \frac{P_t G_t}{4\pi R^2} \frac{\sigma A_e}{4\pi R^2}$$

⇒ Average Noise Power

$$N = k T_s B_n$$

⇒ Signal to noise Ratio

$$S/N = P_r/N$$

$$S/N = \frac{P_r G^2 \lambda^2 \sigma}{(4\pi)^3 R^4 k T_s B_n L}$$

⇒ Track Radar Equation

$$S/N = \frac{P_t G^2 \lambda^2 \sigma}{(4\pi)^3 R^4 k T_s B_n L}$$

→ When the location of a target is known and the antenna is pointed toward the target

⇒ Search Radar Equation

$$S/N = \frac{P_{av} A_e \sigma}{4\pi R^4 k}$$

→ When the target location is known and the radar has the search of target angular region to find it.

(PART. b) Explain working principle of Satellite Communication System (GPS) and difference between triangulation and Trilateration?

(Ans). Principle of Satellite Communication:

- A geostationary Communication Satellite is basically a relay station in space.
- It receives signal from one earth station, amplifies it, improves the signal quality and radiate the signal back to other earth stations.
- Such a relay system allows us to communicate with any corner of the world.
- The use of orbiting satellites to relay transmission from one satellite dish to another or multiple dishes.
- GPS satellite circle the earth twice a day in a very precise orbit and transmit signal information to earth

Triangulation Vs. Trilateration

Triangulation

1. All angles are measured in triangulation.
2. Distance of baseline is measured to control scale error.
3. Intervisibility between stations is essential.
4. Some check base lines are also measured to control scale error.
5. There are more internal checks in the same geometric figure.
6. The side lengths are computed on the basis of measured angles applying sine law.

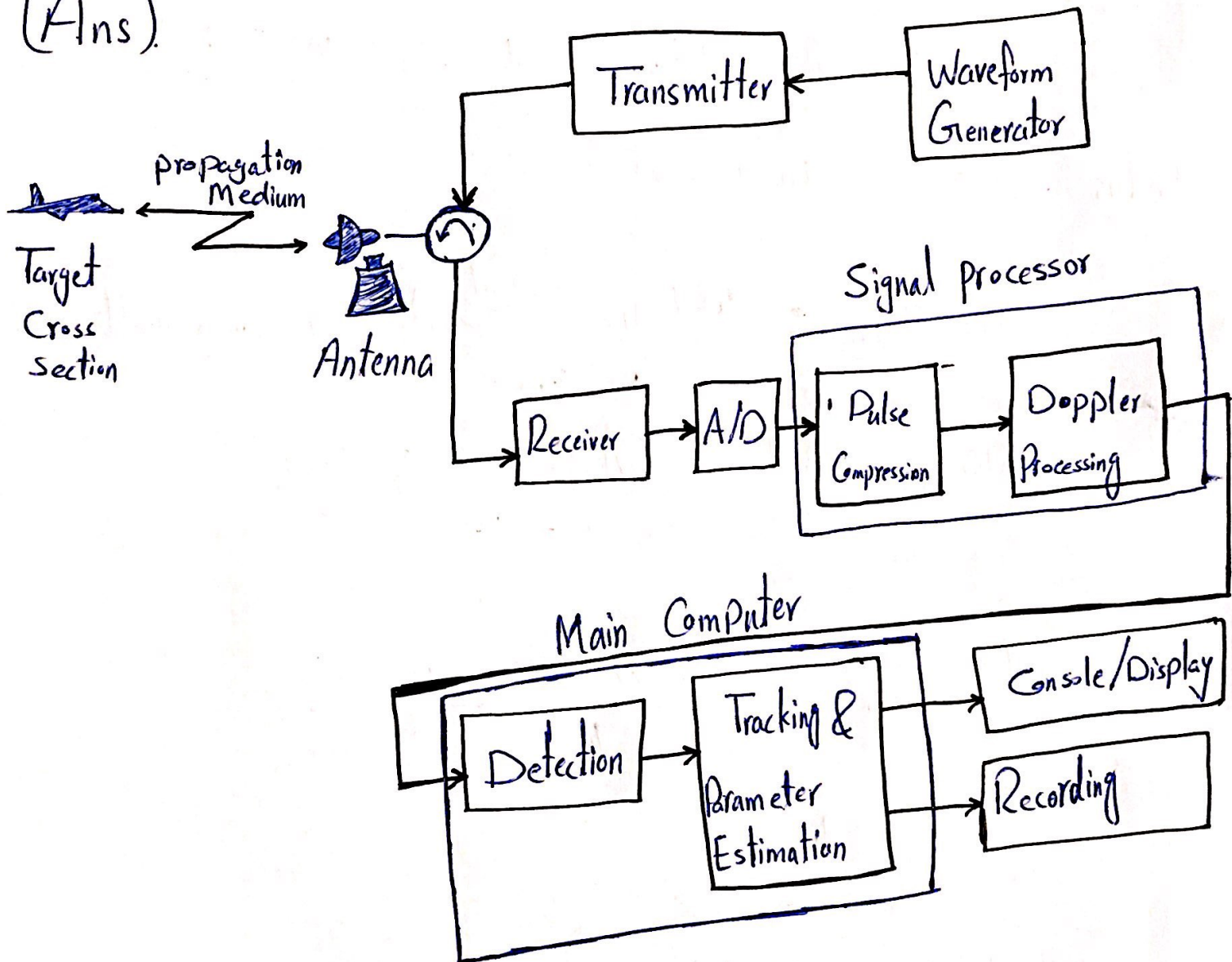
Trilateration

1. All sides are measured in trilateration.
2. Azimuth of the initial line is measured.
3. Some check angles are measured to control azimuth error.
4. For small areas it is possible to measure distances without intervisibility.
5. There are less internal checks in comparison with triangulation in the same geometric figure.
6. The angles are computed on the basis of measured side lengths applying cosine law.

(Q2).

PART(a). Draw and Explain Radar Block Diagram?

(Ans)



Explanation: Basic Radar System Block Diagram Consists of a transmitter and a receiver, each connected to a directional antenna.

The transmitter is capable of sending out a large UHF or microwave power through the antenna.

The receiver collects as much energy as possible from the echoes reflected in its direction by the target and then processes and displays this information in suitable way.

The receiving antenna is very often the same as the transmitting antenna.

(Q₂).

PART (b). Find the escape velocity of satellite?

(Ans).

Consider a body of mass 'm' which is at rest on the surface of the earth.

Let M be the mass of the earth and R be the radius of the earth.

Then the binding energy of the body on the surface of the earth is given by.

$$B.E. = \frac{GMm}{R}$$

Where G is Universal gravitational Constant.

Therefore, KE of satellite = BE

$$KE = \left(\frac{GMm}{R} \right)$$

• Therefore, $\frac{1}{2} m v_c^2 = \left(\frac{GMm}{R} \right)$

$$v_c^2 = \frac{2GM}{R}$$

$$v_c = \sqrt{\frac{2GM}{R}}$$

$$V_c = \sqrt{\frac{2GM}{R}}$$

Here, $G = 6.67 \times 10^{-11}$, $M = 5.97 \times 10^{24}$

$$R = 6378000$$

$$= \sqrt{\frac{2(6.67 \times 10^{-11})(5.97 \times 10^{24})}{6378000}}$$

$$= \sqrt{\frac{2 \times 6.67 \times 5.97 \times 10^{24-11}}{6378000}}$$

$$= \sqrt{\frac{79.72 \times 10^{13}}{6378000}}$$

$$= \sqrt{124992160}$$

$$= 1118 \text{ m/s or } 11.2 \text{ km/s}$$

(Q3).

PART (a). Find out the orbital speed & Time Period of Satellite?

(Ans). Orbital speed:

It is the minimum speed required to put satellite in given orbit around earth.

$$V = \sqrt{\frac{GM}{r}} = \sqrt{\frac{gR^2}{r}}$$

Where, $g = 9.8 \text{ m/s}^2$ and $R_e = \text{radius of earth.}$

The value of orbital velocity was found to be 7.9 km/s .

$$V = R \sqrt{\frac{g}{R+h}}$$

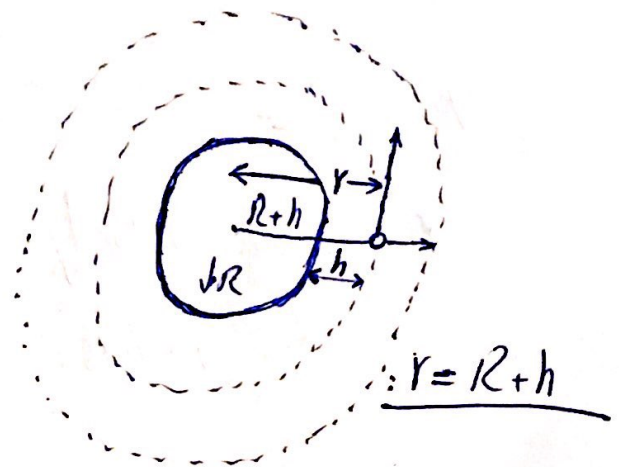
Satellite is close to earth

$$R+h \approx R$$

$$V = R \sqrt{\frac{g}{R}}$$

$$V = \sqrt{g \times R} = \sqrt{gR}$$

$$V = 7.92 \times 10^3 \text{ m/s.}$$



Time Period of Satellite:

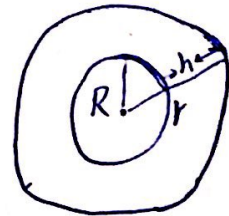
Time taken by satellite for one complete revolution around earth.

$$T = \frac{\text{Distance travelled in one revolution}}{\text{Orbital speed}} = \frac{2\pi r}{v} = \frac{2\pi r}{R\sqrt{g/r}}$$

$$T = \frac{2\pi r}{R} \sqrt{\frac{r}{g}} = \frac{2\pi}{R} \sqrt{\frac{r^3}{g}}$$

$$T = \frac{2\pi}{R\sqrt{g}} \sqrt{r^3}$$

$$= \frac{2\pi}{R\sqrt{g}} \sqrt{(R+h)^3}$$



$$v = \sqrt{\frac{g}{r}}$$

it is independent of mass of satellite.

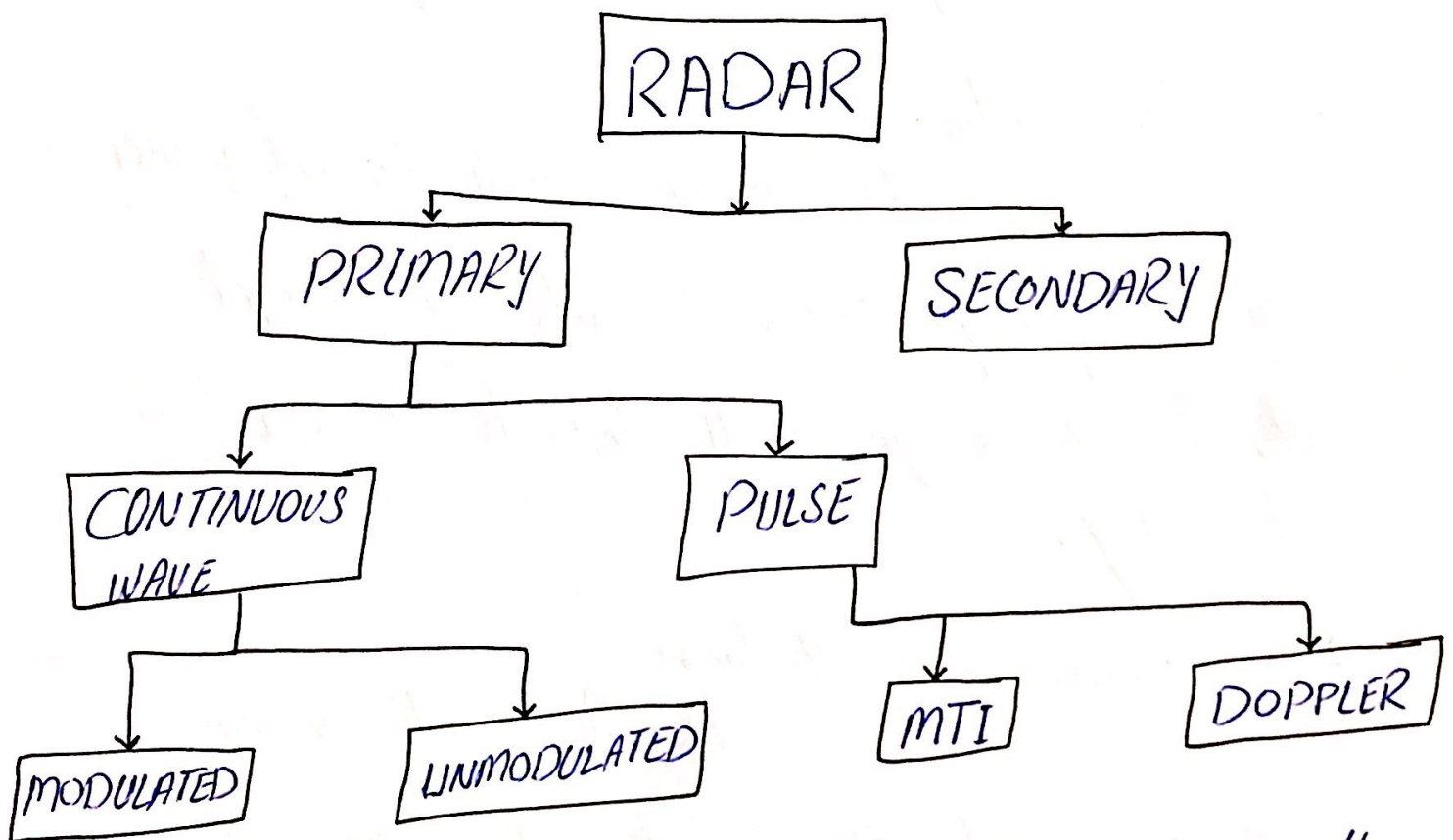
$$v \propto \frac{1}{\sqrt{r}}$$

orbital velocity decrease with increase in orbital radius.

(Q3).

PART (b). Explain different types of radar Systems?

(Ans) TYPES OF RADAR



Primary Radar :- primary radar relies solely on the energy that it has generated and radiated, being reflected back from the target.
i.e. echo.

Secondary Radar → It has some co-operation from the target. The target generates its own 'em' radiation.

There for Primary Radar has following types:-

1). **Pulse Radar**:- It sends high ~~speed~~ power and frequency pulses towards the target object. The range will depend on repetition frequency.

2). **Continuous wave Radar** → It does not measure the range of the target but rather the rate of change of range by measuring the doppler shift of the return signals.