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①

Subject: Numerical Analysis

Q 1
a

Find the polynomial of degree 3 or less that interpolates the points $(0, 2)$, $(1, 1)$, $(2, 0)$ and $(3, -1)$

Soln ⇒

The Lagrange form is as follows:

$$P(x) = 2 \frac{(x-1)(x-2)(x-3)}{(0-1)(0-2)(0-3)} + 1 \frac{(x-0)(x-2)(x-3)}{(1-0)(1-2)(1-3)}$$

$$+ 0 \frac{(x-0)(x-1)(x-3)}{(2-0)(2-1)(2-3)} - 1 \frac{(x-0)(x-1)(x-2)}{(3-0)(3-1)(3-2)}$$

$$= -\frac{1}{3} (x^3 - 6x^2 + 11x - 6) + \frac{1}{2} (x^3 - 5x^2 + 6x)$$

$$- \frac{1}{6} (x^3 - 3x^2 + 2x)$$

$$P(x) = -x + 2$$

There exists exactly one interpolating polynomial of degree 3 or less, but it may or may

Name: Sajid Ahmad

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ID: 12671

②

Subject: Numerical Analysis

are not be exactly degree 3.

the data points are collinear, so

the interpolating polynomial has degree

1. there are no interpolating

polynomial of degree 2 or 3.

It may be already intuitively

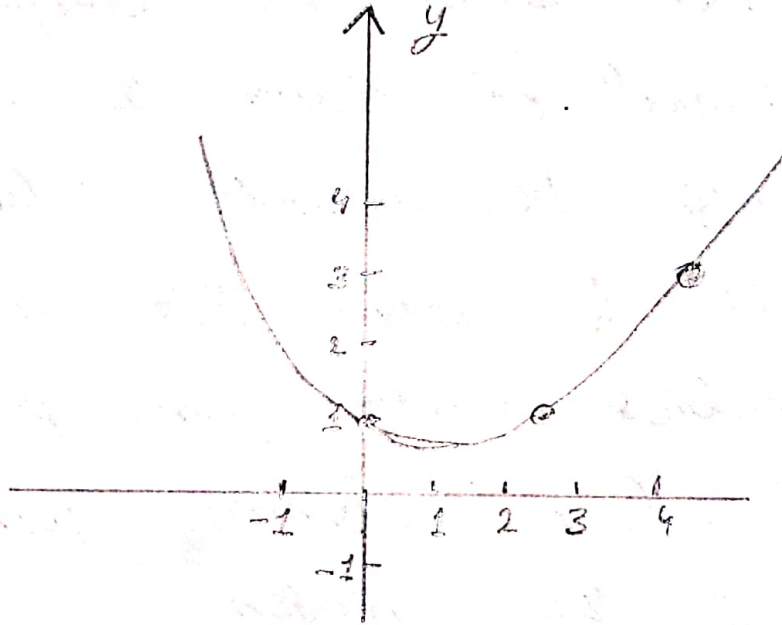
obvious to you that no parabola

or cubic curve can pass

through four collinear points, but

here is the reason.

Q1
 (b) Find an interpolating polynomial for the data points $(0, 1)$, $(2, 2)$ and $(3, 4)$ for the figure given below.



Sol:

Interpolation by parabola. The points as $(0, 1)$, $(2, 2)$ and $(3, 4)$ are interpolated by the function

$$P(x) = \frac{1}{2}x^2 - \frac{1}{2}x + 1.$$

Substituting into Lagrange's formula

$$P_2(x) = 1 \frac{(x-2)(x-3)}{(0-2)(0-3)} + 2 \frac{(x-0)(x-3)}{(2-0)(2-3)} + 4 \frac{(x-0)(x-2)}{(3-0)(3-2)}$$

$$P_2(x) = \frac{1}{6}(x^2 - 5x + 6) + 2\left(-\frac{1}{2}\right)(x^2 - 3x) + 4\left(\frac{1}{3}\right)(x^2 - 2x)$$

$$= \frac{1}{2}x^2 - \frac{1}{2}x + 1$$

Check that $P_2(0) = 1$, $P_2(2) = 2$, and $P_2(3) = 4$,

Suppose that we presented with n points $(x_1, y_1), \dots, (x_n, y_n)$. For each k between 1 and n , define the degree $n-1$ polynomial

$$L_k(x) = \frac{(x-x_1)\dots(x-x_{k-1})(x-x_{k+1})\dots(x-x_n)}{(x_k-x_1)\dots(x_k-x_{k-1})(x_k-x_{k+1})\dots(x_k-x_n)}$$

The interesting property of L_k is that $L_k(x_k) = 1$, while $L_k(x_j) = 0$, where x_j is any of the other data points. Then ~~the~~ define the degree $n-1$ polynomial

$$P_{n-1}(x) = y_1 L_1(x) + \dots + y_n L_n(x).$$

Name: Sajid Atmad Patrone: BE(E)

ID: 12671

⑤ Subject: Numerical Analysis

This is a straight forward generalization of the polynomial and work same way. Substituting x_k for x yields.

$$P_{n-1}(x_k) = y_1 L_1(x_k) + \dots + y_n L_n(x_k) = 0$$
$$+ \dots + 0 + y_k L_k(x_k) + 0 + \dots + 0 = y_k$$

So it works as designed.

Q2a

Use the two-point forward difference formula with $h=0.1$ to approximate the derivative of $f(x) = \frac{1}{x}$ at $x=2$.

Solⁿ o

Use formula

$$f'(x) \approx \frac{f(x+h) - f(x)}{h}$$

put the values.

$$f'(x) = \frac{f(2+0.1) - f(\frac{1}{2})}{0.1}$$

$$f'(x) = \frac{\frac{1}{2.1} - \frac{1}{2}}{0.1} \quad \therefore$$

$$f'(x) = \frac{-0.02386}{0.1}$$

$$f'(x) = 0.2386$$

the difference b/w the approximation derivative.

$f'(x) = -x^{-2}$ at $x=2$ is the error

Name: Sajid Ahmad. Programme: BE (E)

ID: 12671. Subject: Numerical Analysis

put the values of $f'(x)$ and $x = 2$

$$-0.2381 = -2^{-2}$$

$$-0.2381 = (-0.25)$$

$$-0.2381 - (-0.25)$$

$$f'(x) = 0.0119$$

Now

$$f''(x) = 2x^{-3} \text{ for } c \text{ b/w } 2 \text{ and } 2.1$$

$$f''(x) = 2(0.1)^{-3}$$

$$= 0.0125$$

and

$$(0.1)(2.1)^{-3}$$

$$(0.1) 0.10797 \Rightarrow 0.01079$$

OR

$$= 0.0108$$

A second order formula According to Taylor's theorem.

Name: Sajjad Ahmad

Program: BECE

ID: 12671

8

Subject: Numerical Analysis

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2} f''(x)$$

$$f(2+0.1) = \frac{1}{2} + 0.1(0.0119) + \frac{(0.1)^2}{2}(0.0108)$$

$$f(2+0.1) = \frac{1}{2} + 0.00119 + \frac{0.01}{2}(0.0108)$$

$$f(2+0.1) = 0.50119 + 0.00054$$

$$f(2+0.1) = 0.50659$$

$$f(2.1) = 0.50659$$

$$f(x) = 1.063839$$

$$f(x-h) = f(x) - hf'(x) + \frac{h^2}{2} f''(x)$$

$$f(2-0.1) = \frac{1}{2} - 0.1(0.0119) + \frac{(0.1)^2}{2}(0.0108)$$

$$f'(2.1) = \frac{1}{2} - 0.00119 + \frac{0.01}{2}(0.0108)$$

$$f'(2.1) = \frac{1}{2} - 0.00119 + 0.00054$$

$$f'(2.1) = 0.5 - 0.00119 + 0.00054$$

$$f'(2.1) = 0.49881 + 0.00054$$

$$f'(2.1) = 0.49935$$

$$f'(x) = 0.49935 (2.1)$$

$$f'(x) = 1.048635$$

where

$$x-h < 2 < x+h$$

$$f'(x) = \frac{f(x+h) - f(x-h)}{2h}$$

$$f'(x) = \frac{f(2+0.1) - f(2-0.1)}{2(0.1)}$$

$$f'(x) = \frac{(2.1) - (1.9)}{0.2}$$

$$1.048635 = \frac{(2.1) - (1.9)}{0.2}$$

$$1.048635 = \frac{0.2}{0.2}$$

$$1.048635 = 1$$

$$1 - 1.048635$$

$$f'(x) = -0.048635 \quad \text{Ans}$$

Q 2(b)

Use Newton's divided differences to find the interpolating polynomial passing through the points (0, 1), (2, 2) and (3, 4).

Solⁿ →

Apply the definitions of divided difference leads the following table.

0	1		
		$\frac{1}{2}$	
2	2		$\frac{1}{2}$
		2	
3	4		

This table is compute as follows
After writing down the x and y coordinate in separate columns. calculate the next columns. left to right as divided differences

$$\frac{2-1}{2-0} = \frac{1}{2}$$

$$\frac{2 - \frac{1}{2}}{3-0} = \frac{1}{2}$$

$$\frac{4-2}{3-2} = 2$$

P.T.O

After completing the divided differences triangle, the coefficients of polynomial $1, \frac{1}{2}, \frac{1}{2}$ can be read from the top edge of the table.

The interpolating polynomial can be written as

$$P(x) = 1 + \frac{1}{2}(x-0) + \frac{1}{2}(x-0)(x-2)$$

Or instead form

$$P(x) = 1 + (x-0)\left(\frac{1}{2} + (x-2) \cdot \frac{1}{2}\right)$$

the base points for the nested form are $x_1 = 0$ and $x_2 = 2$. Alternatively we could do more algebra and write the interpolating polynomial

$$P(x) = 1 + \frac{1}{2}x + \frac{1}{2}x(x-2) = \frac{1}{2}x^2 + 1.$$

Ans.

12

Q3
Q

Solve the least squares problem:

$$\begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -3 \\ 15 \\ 9 \end{bmatrix}$$

Sol:

$$\begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -3 \\ 15 \\ 9 \end{bmatrix}$$

The normal equations $A^T Ax = A^T b$ are

$$\begin{bmatrix} 9 & 6 \\ 6 & 29 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 45 \\ 75 \end{bmatrix}$$

Solution of the normal equations are

$\bar{x}_1 = 3.8$ and $\bar{x}_2 = 1.8$ the residual vector is

$$r = b - A\bar{x} = \begin{bmatrix} -3 \\ 15 \\ 9 \end{bmatrix} - \begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 3.8 \\ 1.8 \end{bmatrix}$$

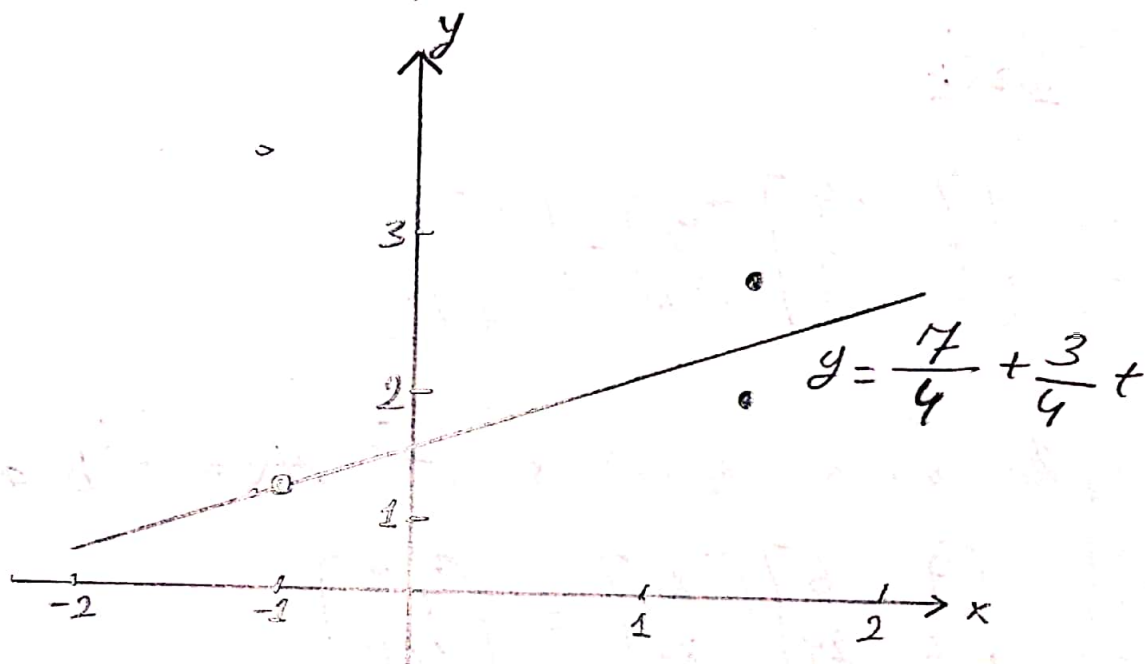
$$= \begin{bmatrix} -3 \\ 15 \\ 9 \end{bmatrix} - \begin{bmatrix} -3.4 \\ 13 \\ 11.2 \end{bmatrix} = \begin{bmatrix} 0.4 \\ 2 \\ -2.2 \end{bmatrix}$$

which has Euclidean norm $\|e\|_2$

$$= \sqrt{(0.4)^2 + 2^2 + (-2.2)^2} = \boxed{3} \text{ Ans}$$

13

Q3(b) Find the line that best fits the three data points $(t, y) = (1, 2)$, $(-1, 1)$ and $(1, 3)$ in the figure below.



Solo →

The model is $y = C_1 + C_2 t$ and the goal is to find the best C_1 and C_2 . Substitution of the data points into the model yields.

$$C_1 + C_2(1) = 2$$

$$C_1 + C_2(-1) = 1$$

$$C_1 + C_2(1) = 3$$

or in matrix form

matrix form

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$$

We know that

This system has no solution (C_1, C_2) for two separate reasons first, if there is a solution then the $y = C_1 + C_2x$ would be a ~~linear~~ line containing the three data points. However it is easily seen that points are not collinear. This is the system

$$\text{of equation } \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$$

and we ~~had~~ found that the best solution in terms of least squares is $(C_1, C_2) = \left(\frac{7}{4}, \frac{3}{4}\right)$ therefore

(15)

the best lines is $y = \frac{7}{4} + \frac{3}{4}t$

we can evaluate the fit by using the statistics defined earlier. the residuals at the data points are.

t	y	line	error
1	2	2.5	-0.5
-1	1	1.0	0.0
1	3	2.5	0.5

and the RMSE is $\frac{1}{\sqrt{6}}$ as seen earlier.

the previous example suggests a three-step program for solving least squares data-fitting problems.

Fitting data by least squares.

Given a set m data points (t_1, y_1) , \dots , (t_m, y_m) .

Step 1: \rightarrow

Choose a model. Identify a parameterized model, such as $y = c_1 + c_2 t$, which will be used to fit the data.

Name : Sajid Ahmad

Program : BE (E)

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(16) Subject : Numerical Analysis

Step 2 :->

Force the model to fit the data. Substitute the data points into the model. Each data point creates an equation whose unknown are the parameters, such as C_1 and C_2 in the line model. This results in a system $Ax = b$, where the unknown x represents the unknown parameters.

Step 3 :->

Solve the normal equations. The least squares solution for the parameters will be found as the solution to the system of normal equations $A^T Ax = A^T b$