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Dept :- BE (E)

Subject :- Signal & Systems.

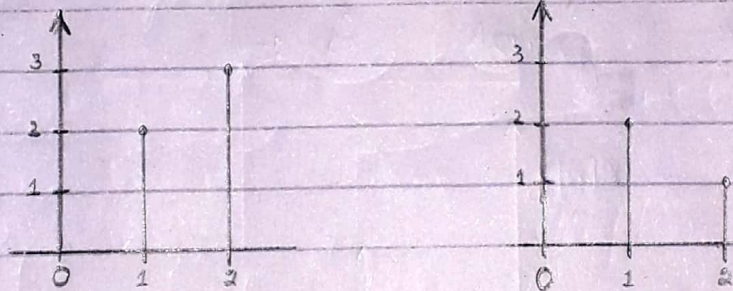
mm x mm x mm x mm

Q1:-

a)

Ans:-

As we are given the graphs :-



The summation is called the convolution sum of the sequence $x[n]$ & $h[n]$ and represented compactly as:

$$y[n] = x[n] * h[n]$$

As we know:-

$$x[n] = 2x[n] + 2[x-1] + 3x[n-2]$$

and

$$y[n] = 3x[n] + 2x[n-1] + x[n-2].$$

So:-

$$x[n] = x[0]\delta[n] + x[1]\delta[n-1] + x[2]\delta[n-2]$$

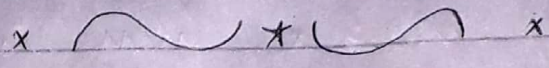
$$y[n] = x[0]\delta[n] + x[1]\delta[n-1] + x[2]\delta[n-2].$$

Then:-

$$x[n] = \sum_{k=0}^2 x[m] \delta[n-k]$$

for

$$Y[n] \rightarrow Y[n] = \sum_{k=0}^2 x[m] \delta[n-k]$$



Q1:-

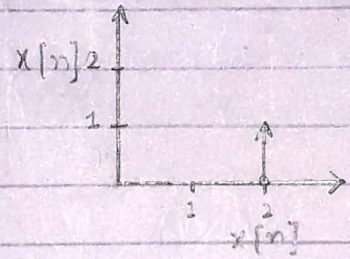
b)-

Ans:-

Given:-

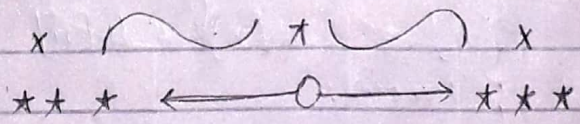
$$Y[m] = x[m] + x[m-2]$$

The graph is :-



(a)

So the graph "a" shows us the given system.



Q.2:-

b)-

i)-

Ans:-

$$Y[n] = x^2[n]$$

This system is non-invertible because we cannot determine the sign of the input from knowledge of output.

Q2:-

b)

ii)-

Ans:-

$$Y[n] = x[n+2]$$

This system is non-causal because its output involves future value of the input so it's called non-causal.

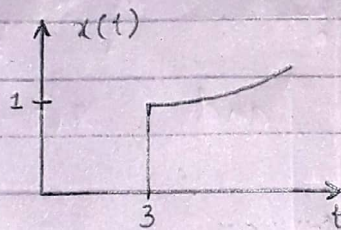
x ~~~~~ x

Q2:-

a)-

Ans:-

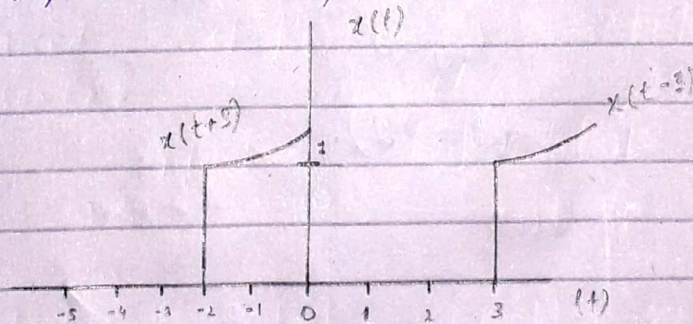
Given graph:-



i)- $x(t+5)$ and $x(3t)$.

$$y(t) = x(t-3), \quad (t) = x(t+5)$$

So:-



Above figure shows translation which is from right to left.

$$\text{At } t=3, \quad x(t)=1$$

$$\text{At } t+5=3, \quad x(t)=1$$

$$t = -5+3$$

$$(t = -2)$$

Compression $\rightarrow x(3t)$.

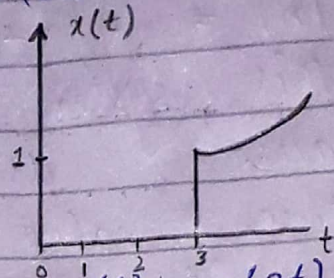
$$\text{At } t=3, \quad x(t)=1.$$

$$\text{At } 3t=3, \quad x(3t)=1.$$

$$3t=3$$

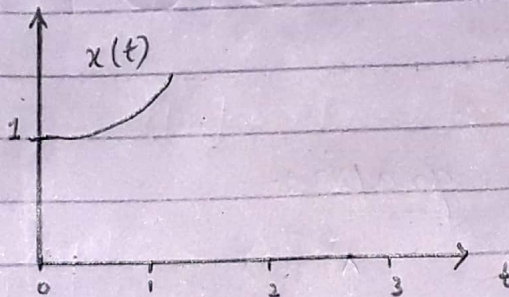
$$t = \frac{3}{3}$$

$$t=1$$



So:-

$$y(t) = x(t-3), \quad z(t) = x(3t).$$



ii) - $x(t/4)$ and $x(t-2)$.

Expansion :-

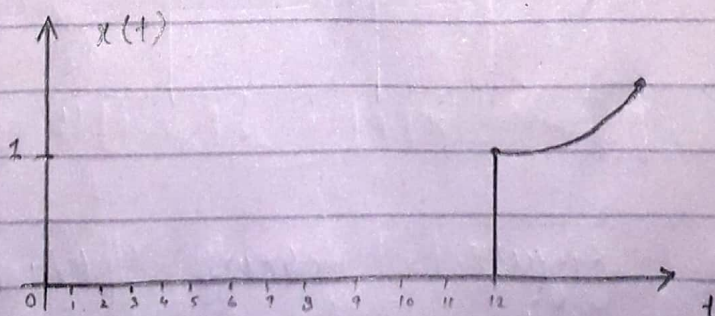
$$x(t/4) :-$$

$$\text{At } t=3, \quad x(t)=1.$$

$$\text{At } t/4=3, \quad x(t/4)=1.$$

$$t/4=3$$

$$(t=12).$$



Time delay:-

$$x(t-2)$$

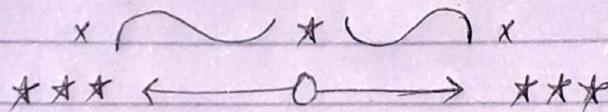
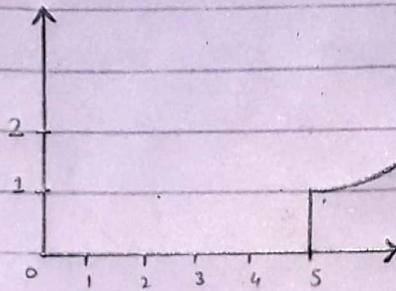
$$\text{At } t=3, \quad x(t) = 1$$

$$\text{At } t-2=3, \quad x(t) = 1.$$

$$t = 2+3$$

$$(t=5).$$

So:-



Q3:-

Ans:-

>

If a time shift in the input signal results in an identical time shift in the output signal, the system is said to be "Even".

The

End