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## Final Term

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Q no 3 :-

Ans :- The most suitable component of an operating system that is suited to ensure fair, secure, orderly and efficient use of memory is memory management system. The task of memory management includes keeping track of used and free memory space all well as when where and how much memory to allocate and deallocate. It is also responsible for swapping process in and out of main memory. The purpose of a memory management is to ensure fair, secure, orderly and efficient use of a memory.

Q no.:

Ans.:

Dynamic Loading:-

other routine is loaded during or  
run-time and it is not

Supported by OS.  
Dynamic loading is the process  
of loading the dependent library  
or routine on demand or

at some time at run time, load  
time (The time which the main

program executable is loaded in  
Contrast to loading all  
dependencies at load time together

with the main program

The window loaded for example

Support both techniques. The  
loading process complete when  
the library has been

Successfully loaded into  
main memory.

Examples

when we write  
a program in language  
we are going to execute  
the same program

if { }  
move ( )

## Dynamic Linking

System library or other routine is loaded during run-time and its supported by OS.

When the program attempt to call an imported function for the first time, that library that contains that function they may not have been loaded yet, initially

the compiler place a temporary small function called a stub that gets called instead of the

important function. The stubs call

into the OS. If the library

is currently not loaded it get loaded (this ~~is~~ step is called <sup>loading</sup> dynamic)

Then the stub is modified so

that it call the important function directly the next

time it gets called. This

process is called dynamic linking

In Dynamic Linking when a

module need to be called

that module is loaded into memory

and a link b/w the calling module is

established by the stub which is

the piece of the code that is linked

in linking time program

Qno 6:-

Ans:- First-Fit:-

Allocate into the first ~~available~~ available gap found of adequate size, starting from the beginning of memory region list. Scan memory region list from start for First-Fit must always skip over many regions at the start of list.

②:- Next-Fit:-

Allocate into the first available gap - found remaining the search from the last allocation.

Scan memory region list from the point of last allocation to next fit. Breaks up large block at the end of memory.

③ Best-Fit

Pick the smallest free region in the entire list. Leaves small unusable region and slows due to searching of entire list.

## ④ worst-fit

The worst-fit in the entire list leaves small spaces as it searches the entire list. Fragmentation still an issue.

## Qnos:-

### Ques:- Internal Fragmentation

memory block assigned to process is bigger. Some portion of memory is left unused as it cannot be used by another process.

### External

Total memory space is enough to satisfy a request or to reside a process in it but it is not contiguous. So it cannot be used. External fragmentation can be reduced by compaction or ~~to~~ shuffle ~~to~~ memory content.

### Internal

① In internal fragmentation fixed sized memory block always available appointed to process.

### External

① In external fragmentation variable-sized memory block always appointed to method.

## ② Internal Fragmentation

happen when the method or process is larger than the memory

③ The solution of internal fragmentation is best fit block

④ Internal fragmentation occur when memory is divided into fixed size partition

⑤ The difference b/w memory allocate and required space

## ② External Fragmentation

happen when the method or process is removed

③ solution of external is compaction, paging and Segmentation

④ when memory is divided into variable size partition based on the size of process

⑤ The unused space formed b/w non-contiguous memory.

Q no 3:-

Ans. Yes It is necessary to check that either Safe State exist or not in deadlock prevention because when we disallow deadlock by setting "Safe States", it mean process completion is always ~~not~~ guaranteed.

Q no 4:-

~~Symmetric~~ Difference B/w Symmetric and Asymmetric

- Symmetric encryption use a single key that need to be shared among the people who need to receive the message while asymmetrical encryption uses a pair of public key and a private key to encrypt and decrypt message when communicating
- Symmetric encryption is an old technique while Asymmetric encryption is relatively new.
- Asymmetric encryption was introduced to complement the inherent problem of the need to share the key in Symmetrical encryption model, eliminating the need to share the key by using pair public private key

Asymmetric encryption  
takes relatively more  
time than symmetric  
encryption



Q no 7:-

Ans:-

Threads:-

A thread is a sequential execution stream within a process. This means that single process may be broken up into multiple threads. Each thread has its own program counter, register, and stack but they all share the same address space within the process.

Kernel Thread - user-level:

Thread can either be created as kernel thread or user level thread.



depending on the operating system in system that use kernel-level-threads the OS itself is aware of each individual threads. A context switch b/w kernel thread belonging to same process require only registers Program Counter and Stack to be changed the overall memory management information doesn't need to be switched since both of the thread share same address space. Thus context switching b/w two kernel threads is slightly faster than switching b/w two processes.

A user level thread is the thread within within a process which the OS does not know about. In user level threads approach the cost of a context switch b/w threads can be made even lower. Since the OS itself doesn't need to be involved no extra system calls are required.