



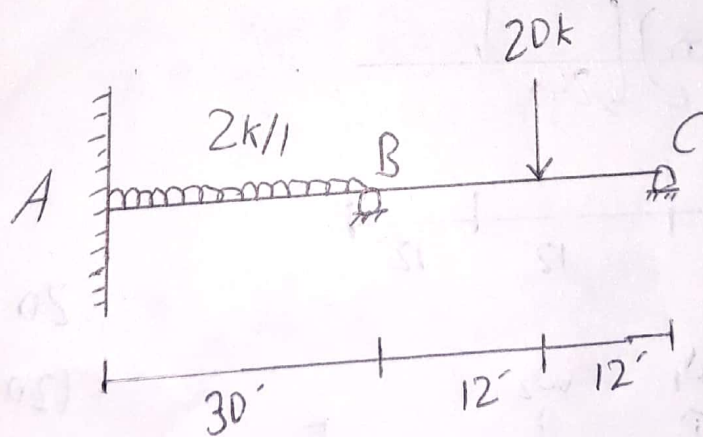
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Section: A

Subject: Structure Analysis-II

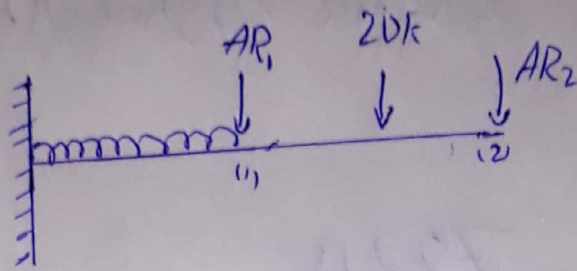
Question No. 1:



Solution:

$$S-I = 2^0$$

Step #01: Select redundant actions

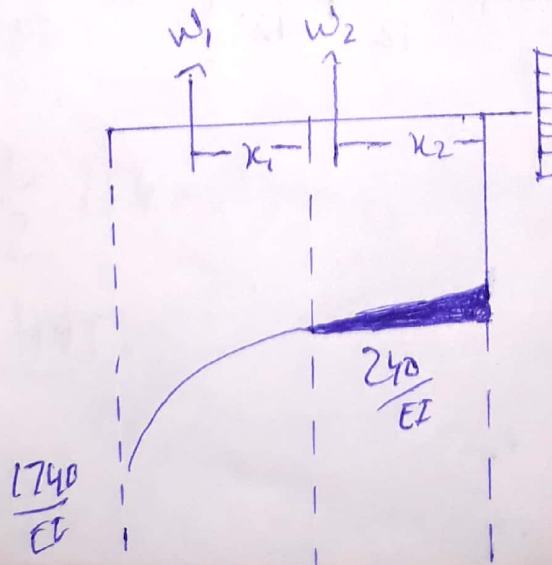
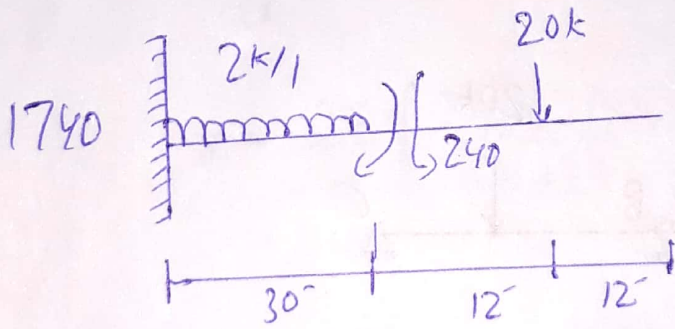


$$\begin{bmatrix} DRS_1 \\ DRS_2 \end{bmatrix} = \begin{bmatrix} ? \\ ? \end{bmatrix} \cdot \begin{bmatrix} AR_1 \\ AR_2 \end{bmatrix} = \begin{bmatrix} ? \\ ? \end{bmatrix}$$

$$[DRS] = [DRL] + F \times AR$$

Step #02:

Compute the values of [DRL]



$$\begin{aligned} 20 \times 12 &= 240 \\ (20 \times 42) + 2 \times 30 \times 1 &= 1740 \end{aligned}$$

$$W_1 = \left(\frac{240+0}{2EI} \right) \times 12 = 1440/EI$$

$$W_2 = \frac{1}{n+1} \times (b \times h) = \frac{1}{2+1} \left(\frac{1100}{EI} \right) \times 30 = 1100/EI$$

$$x_1 = \frac{L}{3} \left(\frac{a+2b}{a+b} \right)$$

$$x_1 = \frac{12}{3} \left(\frac{240+2(0)}{240+0} \right) = 4'$$

$$x_2 = \frac{3}{n+2} \times b = \frac{3}{2+2} (30)$$

$$= 22.5'$$

$$DRL_1 = W_1 (x_1 + 30) = 1440(4+30)$$

$$= 48960$$

$$DRL_2 = W_1 (x_1 + 40) + W_2 (x_2 + 12)$$

$$= 1440(4+40) + 11000(22.5+12)$$

$$DRL_2 = 442860$$

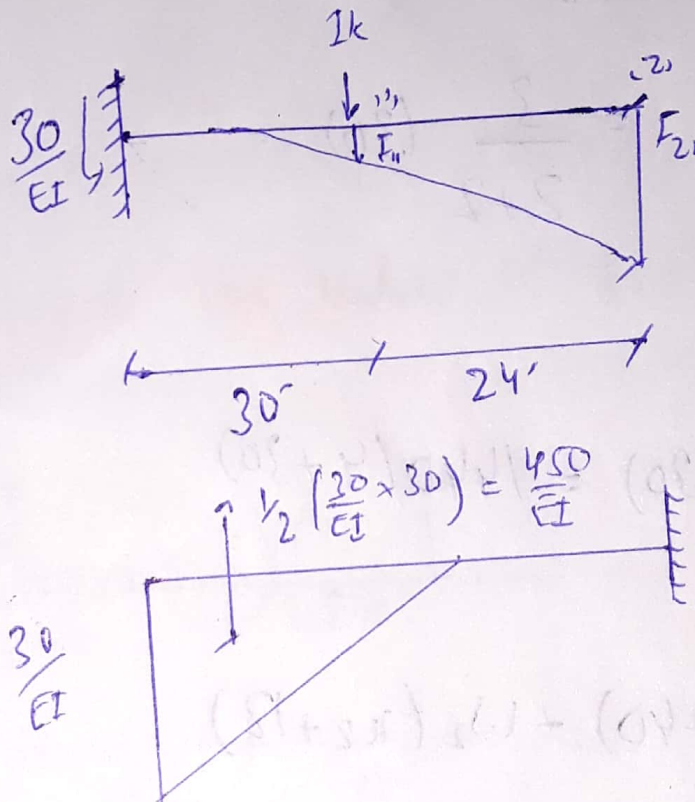
$$[DRL] = \frac{1}{EI} \left[\frac{48960}{442860} \right] = (45+0.05) \frac{22.5}{0}$$

Step # 03:

Construct flexibility coefficient matrix

$$F_{2 \times 2} = \begin{bmatrix} F_{11} & F_{12} \\ F_{21} & F_{22} \end{bmatrix}$$

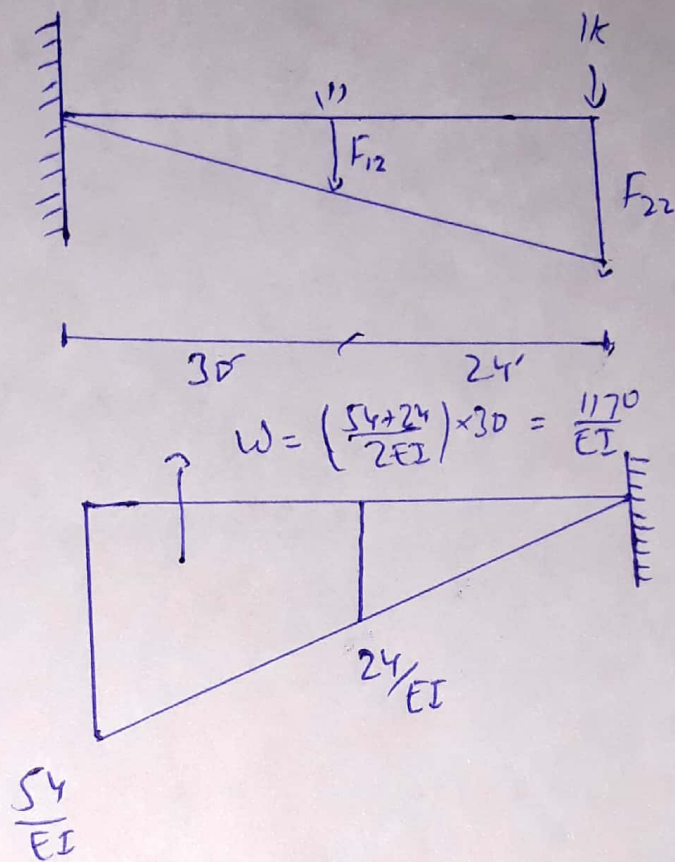
(a) Apply a unit value of AR_1 at reference point
i.e. compute the value of F_{11} & F_{21}



$$F_{11} = \frac{450}{EI} (20) = \frac{9000}{EI}$$

$$F_{21} = \frac{450}{EI} (20 + 24) = \frac{19800}{EI}$$

- b. Apply a unit of AR_2 at reference point (2)
 i. compute the value of F_{12} by F_{22} .



$$x = \frac{30}{3} \left[\frac{24 + 2(54)}{54 + 24} \right] = 16.92'$$

$$F_{12} = \frac{1170}{EI} \times 16.92 = \frac{19800}{EI}$$

$$F_{22} = \frac{1}{2} (54 \times 54) \times \frac{1}{3} (30) + 24$$

$$= \frac{49572}{EI}$$

Question No. 2

Answer.

FORCE METHOD:

- $D_s < D_k$
- Starts with equilibrium of forces
- Forces found by compatibility equations of displacements
- No. of redundants = D_s

METHODS

- Method of consistent deformation
- Column analogy method
- Flexibility matrix method
- Type of indeterminacy:
static indeterminacy

DISPLACEMENT METHOD

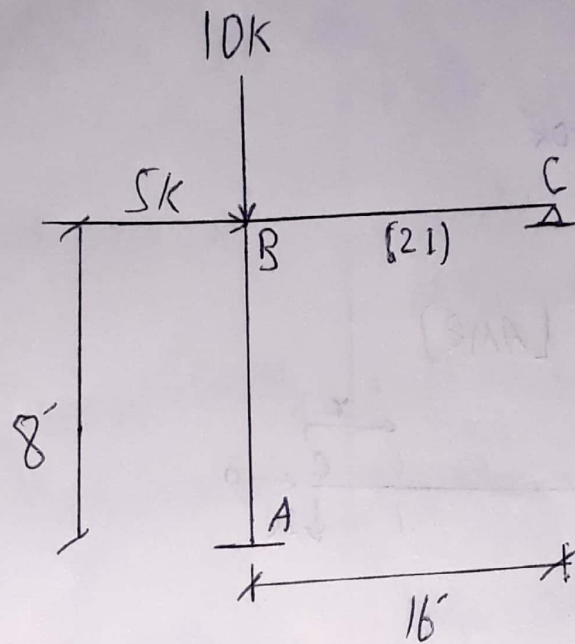
- $D_s > D_k$
- Starts with compatible deformations
- Displacement found by equilibrium equations of forces
- No. of redundants = D_k

METHODS

- Slope deflection method
- Moment distribution method
- Kani's method
- Stiffness matrix method
- Type of indeterminacy
kinematic indeterminacy

Question No. 3

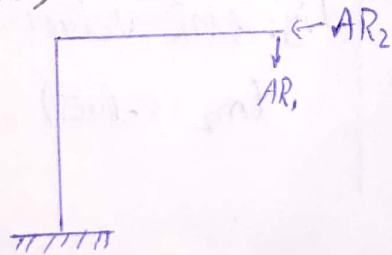
Analyze the rigid-joint frame shown in figure by flexibility method. Assume EI is constant for all members.



Solution:

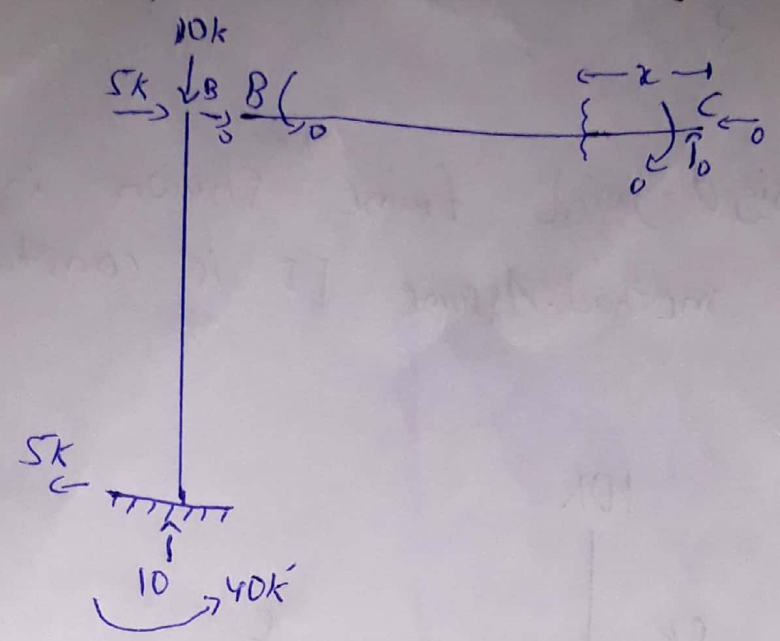
$$\begin{aligned} \text{Total statical indeterminacy} \\ \Rightarrow R - 3 = 5 - 3 = 2^0 \end{aligned}$$

Step #01: Identify Redundant Actions



$$\begin{bmatrix} AR_1 \\ AR_2 \end{bmatrix} = \begin{bmatrix} ? \\ ? \end{bmatrix}, \quad \begin{bmatrix} DRS_1 \\ DRS_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Step # D2: Compute value of [DRL]



Step # D3: [F] or [AMR]

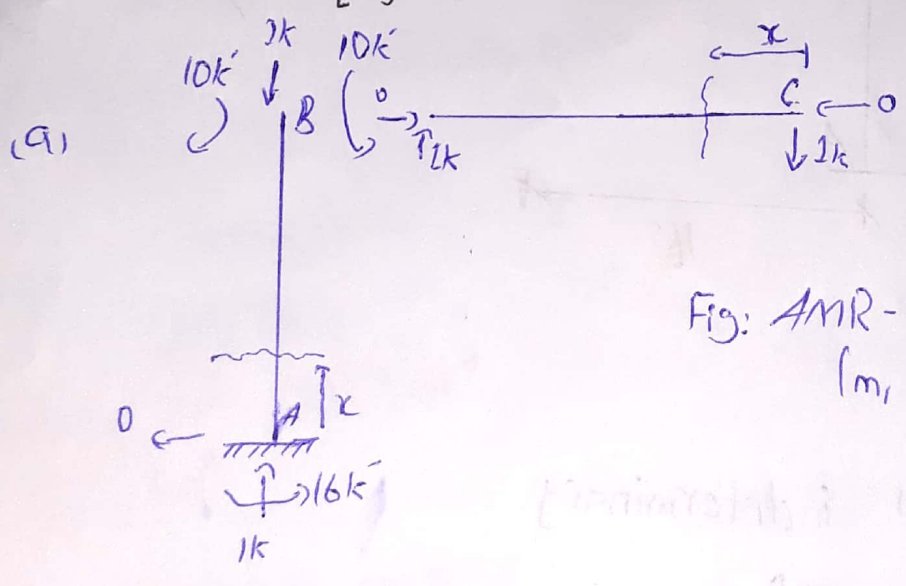


Fig: AMR-Values
(m_1 Values)

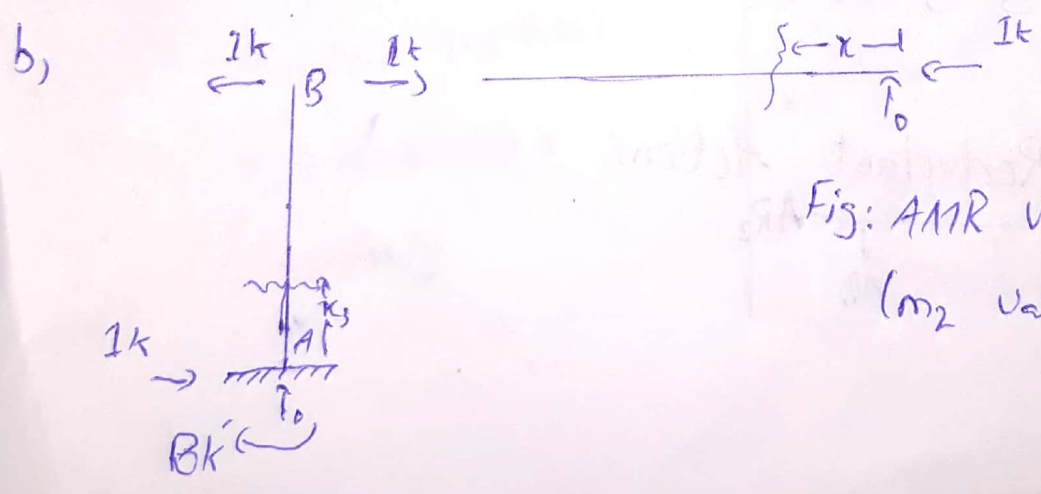


Fig: AMR Values
(m_2 Values)

P.T.D

Member	AB	BC
Origin	A	C
Limits	0-8	0-16
I	I	2I
M	$5x-40$	0
m_1	-16	x
m_2	$8-x$	0

⇒ Finding values of DRL's:

$$\begin{aligned}
 DRL_1 &= \int_0^8 \frac{M_{AB} \cdot m_{1(AB)}}{EI} dx + \int_0^{16} \frac{M_{BC} \cdot m_{2(BC)}}{EI} dx \\
 &= \int_0^8 \frac{(5x-40)(-16) dx}{EI} + \int_0^{16} \frac{0 \cdot x}{EI(2I)} dx
 \end{aligned}$$

$$\boxed{DRL_1 = \frac{2560}{EI}}$$

$$DRL_2 = \int_0^8 \frac{(5x-40)(8-x) dx}{EI} + \int_0^{16} \frac{0 \cdot 0}{EI(2I)} dx$$

$$\boxed{DRL_2 = \frac{-853.33}{EI}}$$

⇒ Compute Flexibility Matrix:

$$F_{2 \times 2} = \begin{bmatrix} F_{11} & F_{12} \\ F_{21} & F_{22} \end{bmatrix}$$

$$\begin{aligned} \Rightarrow F_{11} &= \int_0^8 \frac{M_1^2(AB)}{EI} dx + \int_0^{16} \frac{M_2^2(BC)}{EI} dx \\ &= \int_0^8 \frac{(-16)^2}{EI} dx + \int_0^{16} \frac{x^2}{EI(2)} dx \end{aligned}$$

$$F_{11} = \frac{2730.67}{EI}$$

$$\begin{aligned} F_{12} = F_{21} &= \int_0^8 M_1(AB) \cdot M_2(AB) dx + \int_0^{16} M_2(BC) \cdot M_2(BC) dx \\ &= \int_0^8 \frac{(-16)(8-x)}{EI} dx + \int_0^{16} \frac{(x)(0)}{2EI} dx \end{aligned}$$

$$F_{12} = F_{21} = \frac{-512}{EI}$$

$$\begin{aligned} F_{22} &= \int_0^8 (M_2)_{AB}^2 dx + \int_0^{16} (M_2)_{BC}^2 dx \\ &= \int_0^8 \frac{(8-x)^2}{EI} dx + \int_0^{16} \frac{0^2}{2EI} dx \end{aligned}$$

$$F_{22} = 170.67$$

As we know,

$$[DRS] = [DRL] + [AR] \times [F]$$

$$\Rightarrow [AR] = \frac{[DRS] - [DRL]}{[F]}$$

2. v

$$\Rightarrow [AR] = [F]^{-1} \times (DRS - DRL)$$
$$= \begin{bmatrix} 2730.67 & -512 \\ -512 & 170.67 \end{bmatrix}^{-1} \times \begin{bmatrix} 0 - 2560 \\ 0 + 853.33 \end{bmatrix}$$

$$\begin{bmatrix} AR_1 \\ AR_2 \end{bmatrix} = \begin{bmatrix} -0.00005 \\ 4.997 \end{bmatrix} = \begin{bmatrix} 0 \\ 5 \end{bmatrix}$$