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Q:2:

①

Direct Stiffness Method:

In direct stiffness method
First of all, kinematic indeterminacy of the structure is determined. Kinematic indeterminacy is to number of unknown joints displacements of the structure.

In stiffness method, unknown joints displacements are determined and remaining unknown quantities (Support reactions and Member End Actions) in the structure are functionally dependent on the displacements.

For computing joint displacements, the structure is made restrained (i.e. $K.T=0$) under external loadings and member end actions are calculated for fixed end actions corresponding to unknown joint displacements i.e. (A₀).

Then stiffness matrix is formed and coefficients are calculated under the action of unit displacement corresponding to unknown joint displacements.

If no of unknown joint displacements are 'd', then order of

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Stiffness matrix will be 'dxd'.

②

Coefficients are calculated under the action of unit displacement corresponding to unknown joint displacements. If no. of unknown joint displacements are 'd', then order of

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Stiffness matrix will be 'dxd'.
After computing coefficients of stiffness matrix under the action of unit displacements, the following equation is used to calculate unknown joint displacements.

$$[D] = [S]^{-1} \{ [AD] - [ADL] \}$$

Where

D = unknown joint displacements

[S] = Inverse of Stiffness Matrix

[AD] = External Concentrated Action corresponding unknown joint displacement.

[ADL] = Member End Actions under in restrained structure under external loading.

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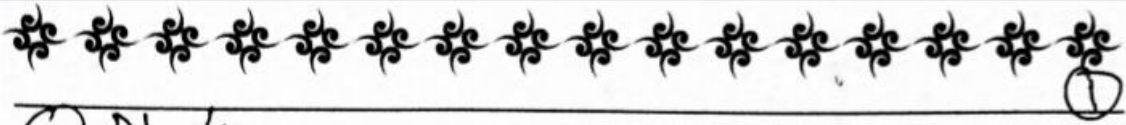
in restrained structure
under external loading.

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Once displacements are found, other unknown structural quantities are functionally dependant on. Computed displacements, and hence can be calculated by method of superposition for the given structure under external loading and under the action of unit displacements.





Q No 4:

In Flexibility method, unknowns to be calculated are joint or support reactions.

Unknown reactions are made redundant and the structure is made statically determinate and analysed for load and actions.

After that, unit forces corresponding to unknown reactions are applied on redundant structure from which flexibility matrix is formed and calculated. Order of flexibility matrix is equal to no of unknown or redundant actions.

This method is also called Force method.

In Stiffness method, unknowns to be determined are joint displacements and for calculating stiffness matrix unit displacements are applied. Order of stiffness matrix is equal to the no of unknown joint displacements i.e Kinematic Indeterminacy.

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Q No 4:

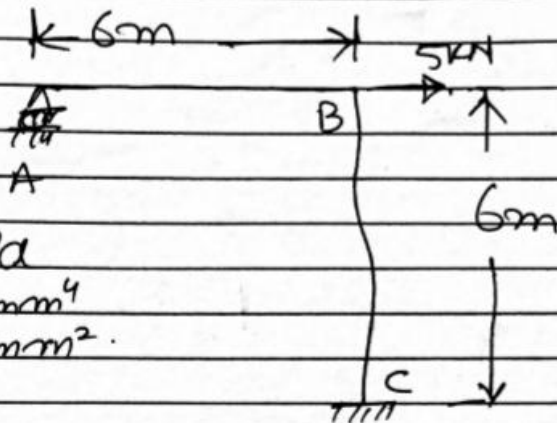
Displacements & Kinematic Indeterminacy

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Q.No. 1:



$$E = 200 \text{ GPa}$$
$$I = 60 \times 10^6 \text{ mm}^4$$
$$A = 600 \text{ mm}^2$$

Deflection and Rotation @ 'B' = ?

Reactions @ Supports = ?

S.F.D and B.M.D = ?

$$\Rightarrow EI = 200 \times 10^9 \times \frac{60 \times 10^6}{(1000)^4} = 12 \times 10^6 \text{ N-m}^2$$
$$= 12000 \text{ kN-m}^2$$

$$EA = 200 \times 10^9 \times \frac{600}{(1000)^2} = 12 \times 10^6 \text{ N}$$
$$= 12000 \text{ kN}$$

New Restained Structure under existing loading is

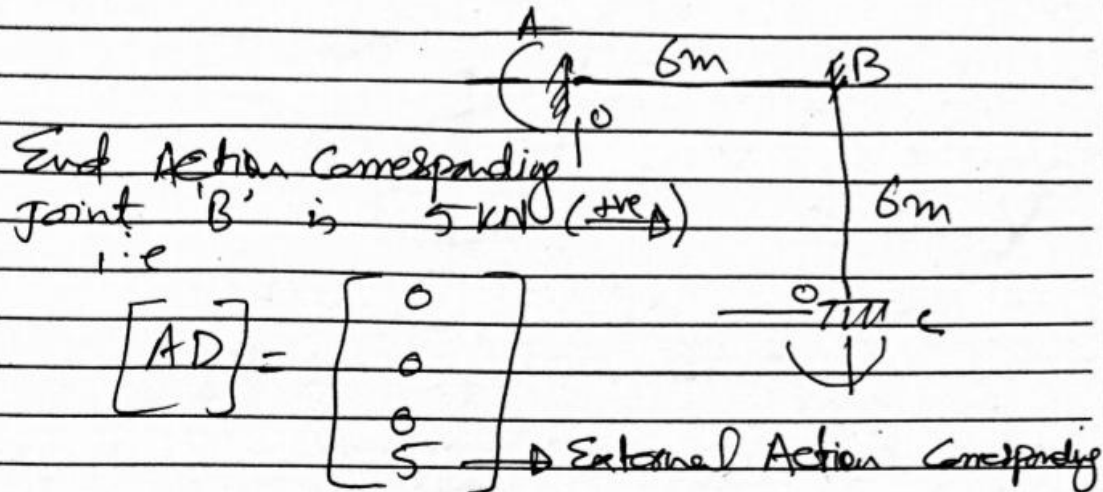
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New Restrained Structure under existing loading is

Darsi Notes

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(2)



End Action on restrained Structure is

$$ADL = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Q_A, Q_B & Δ_A, Δ_B to be determined.

Given structure under unit rotation at (A) remaining structure restrained i.e.



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restrained i.e 0



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$$\frac{4EI}{l} = \frac{4 \times 12000}{6}$$

$$= 8000 \text{ kN-m}$$

$$2EI/l = 4000 \text{ kN-m}$$

$$\frac{6EI}{l^2} = \frac{6 \times 12000}{6 \times 6} = 2000 \text{ kN}$$

$$S_{11} = 8000, S_{21} = 4000, S_{31} = 0, S_{41} = 0$$

Now unit +ve rotation @ B i.e

$$S_{12} = 4000, S_{22} = 16000, S_{32} = 0$$

$$S_{42} = -2000$$

unit +ve translation @ (A) i.e

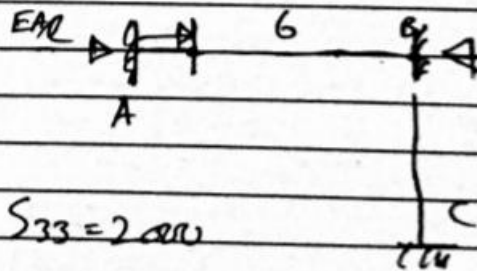
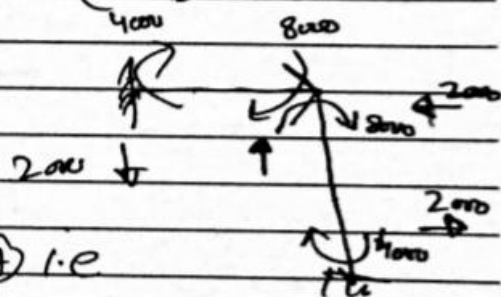
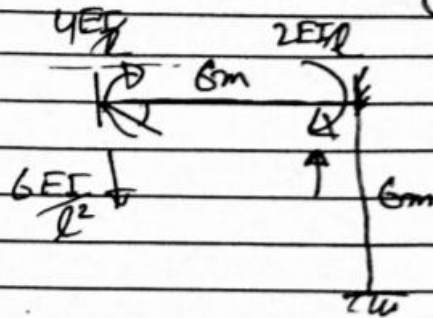
$$\frac{EA}{l} = \frac{12000}{6} (1)$$

$$= 2000 \text{ kN}$$

S_{0}

$$S_{13} = 0, S_{23} = 0, S_{33} = 2000$$

$$S_{43} = -2000$$



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$$S_{43} = -2000$$

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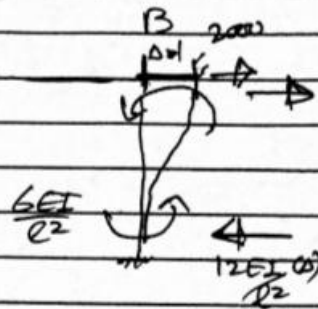
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Now unit true translation @ B i.e

$$\frac{6EI(l)}{l^2} = \frac{6 \times 12000}{6 \times 6} = 2000 \text{ kN-m}$$

$$\frac{12 \times 12000}{6 \times 6 \times 6} = 666.67 \text{ kN}$$



$$S_{44} = 0, S_{24} = -2000, S_{34} = -2000$$

$$S_{44} = 2666.67$$

So, stiffness matrix is

$$[S]_{4 \times 4} = \begin{bmatrix} 8000 & 4000 & 0 & 0 \\ 4000 & 16000 & 0 & -2000 \\ 0 & 0 & 2000 & -2000 \\ 0 & -2000 & 2000 & 2666.67 \end{bmatrix}$$

Now unknown joint displacements can be found from the following equation i.e

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$$\begin{bmatrix} Q_A \\ Q_B \\ \Delta_A \\ \Delta_B \end{bmatrix} = \underset{4 \times 4}{[S]}^{-1} \left\{ [AD] - [ADL] \right\} \quad (5)$$

here $[S]$ calculated on previous page

$$[AD] = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 5 \end{bmatrix} \quad \text{and} \quad [ADL] = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

putting values and solving for unknown displacements, we get.

$$\begin{bmatrix} Q_A \\ Q_B \\ \Delta_A \\ \Delta_B \end{bmatrix} = \begin{bmatrix} -0.001 \\ 0.002 \\ 0.013 \\ 0.013 \end{bmatrix} \quad \left(\begin{array}{l} \text{Unknown displacements} \\ \text{in structure} \end{array} \right)$$

Now, Reactions at ~~sup~~ supports can be calculated as

$$[R] = [R_L] + [S][D]$$

$$[K] = [A]^{-1} [S]$$

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where

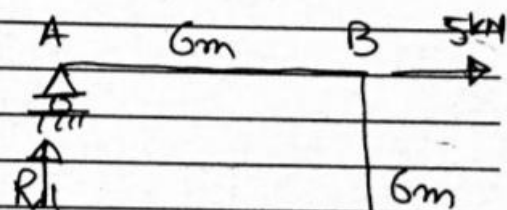
R = Reactions @ Supports

R_r = Reactions on restrained structure due to external loading

$[S]$ = Corresponding Stiffness values

$[D]$ = Displacement Matrix.

$$\begin{bmatrix} R_1 \\ 2 \\ 3 \\ M \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} +$$



$$\begin{bmatrix} -2000 & -2000 & 0 & 0 \\ 0 & 0 & 2000 & 0 \\ 0 & 2000 & 0 & -66.67 \\ 0 & 4000 & 0 & -2000 \end{bmatrix} \times [D]$$

so $R_1 = -2 \text{ kN}$, $R_2 = 0$, $R_3 = -4.7 \text{ kN}$

$M = -18 \text{ kN-m}$.

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$$\left[\begin{array}{ccc|ccc} 0 & 4000 & 0 & -2000 & & \\ \hline \end{array} \right]$$

so $R_1 = -2 \text{ kN}$, $R_2 = 0$, $R_3 = -4.7 \text{ kN}$

$M = -18 \text{ kN-m}$ Darsi Notes

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New Member End Action in ~~2~~ at joint B' and C' is ~~1~~ Structure

$$A_{RE} = \begin{bmatrix} +0 \\ 0 \\ 0 \\ 0 \\ -0 \\ -0 \end{bmatrix} + \begin{bmatrix} 0 & -2000 & -2000 & 2000 & 0 & 0 \\ 4000 & +2000 & 0 & 0 & 0 & 0 \\ 4000 & +16000 & 0 & -2000 & 0 & 0 \\ 0 & 2000 & 0 & -666.67 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 4000 & 0 & -2000 & 0 & 0 \end{bmatrix} \times 10^3$$

$$\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 4.667 & 4.667 \\ 2 & 2 \\ 2 & 2 \\ -4.667 & -4.667 \\ 0 & 0 \\ -18 & -18 \end{bmatrix} \text{ End Actions of Structure}$$

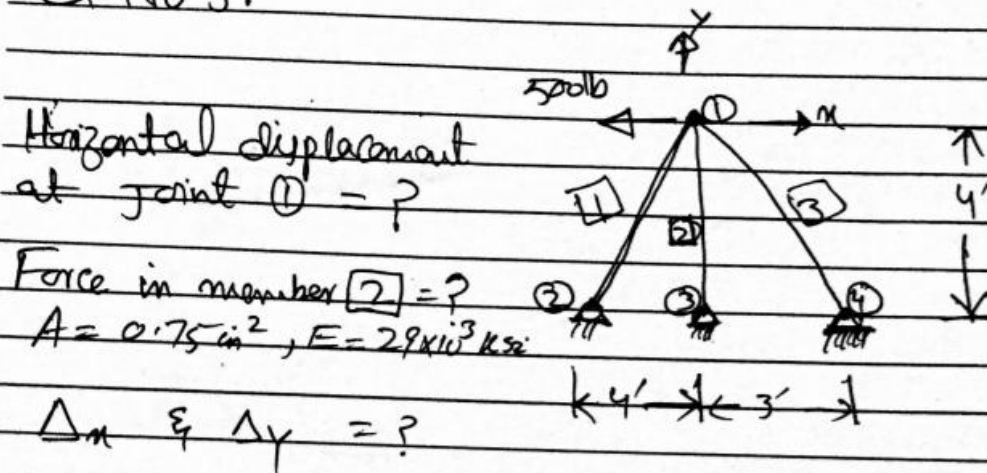
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4	-9.667	-4.667	Structure
5	0	0	
6	-18	-18	

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Q. No 3:



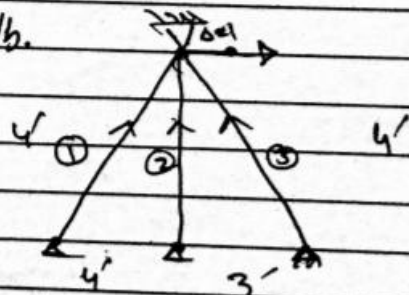
Applying unit true translation along x any y -axis i.e

$$\frac{EA}{L} = \frac{29 \times 10^3 \times 0.75}{6} = 21750 \text{ lb/in}$$

Member ①: $L = 5.657 \text{ ft}$

Member ②: $L = 4 \text{ ft}$

Member ③: $L = 5 \text{ ft}$



Member ①: $\frac{EA}{L} = 320.8 \text{ lb/in}$

Member ②: 453.125 lb/in

Member ③: 369.5 lb/in

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