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(1)

Course Numerical Analysis:

Q1 (a) Find the LU Factorization of the matrix.

$$A = \begin{pmatrix} 1 & 2 & -1 \\ 2 & 1 & -2 \\ -3 & 1 & 1 \end{pmatrix}$$

Soln

The elimination steps proceed as.

$$\begin{pmatrix} 1 & 2 & -1 \\ 2 & 1 & -2 \\ -3 & 1 & 1 \end{pmatrix} \quad \begin{array}{l} \text{subtract } 2 \times \text{row 1} \\ \text{from row 2} \end{array} \quad \begin{pmatrix} 1 & 2 & -1 \\ 0 & -3 & 0 \\ -3 & 1 & 1 \end{pmatrix}$$

$$\begin{array}{l} \text{subtract } -3 \times \text{row 1} \\ \text{from row 3} \end{array} \quad \begin{pmatrix} 1 & 2 & -1 \\ 0 & -3 & 0 \\ 0 & 7 & -2 \end{pmatrix}$$

$$\begin{array}{l} \text{subtract } -\frac{7}{3} \times \text{row 2} \\ \text{from row 3} \end{array} \quad \begin{pmatrix} 1 & 2 & -1 \\ 0 & -3 & 0 \\ 0 & 0 & -2 \end{pmatrix} = U$$

By putting 1's on the main diagonal and the multipliers in the lower triangle in the specific places they were used for elimination. that is.

Q1(a)

(2)

$$L_2 = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -3 & -7/3 & 1 \end{bmatrix}$$

Now check that

$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -3 & -7/3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & 0 \\ 0 & 0 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 2 & -1 \\ 2 & 1 & -2 \\ -3 & 1 & 1 \end{bmatrix} = A$$

The reason that this procedure gives the LU factorization follows from three facts about lower triangular matrices.

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Q 1(b) Find the unknown variables using gaussian elimination methods. (3)

$$\begin{aligned} x + 2y - z &= 3 \\ 2x + y - 2z &= 3 \\ -3x + y + z &= -6 \end{aligned}$$

Sols-

The tablean form as.

$$\left[\begin{array}{ccc|c} 1 & 2 & -1 & 3 \\ 2 & 1 & -2 & 3 \\ -3 & 1 & 1 & -6 \end{array} \right]$$

Two steps are needed to eliminate column 1:

$$\left[\begin{array}{ccc|c} 1 & 2 & -1 & 3 \\ 2 & 1 & -2 & 3 \\ -3 & 1 & 1 & -6 \end{array} \right]$$

Subtract $2 \times$ row 1 from row 2

$$\left[\begin{array}{ccc|c} 1 & 2 & -1 & 3 \\ 0 & -3 & 0 & -3 \\ -3 & 1 & 1 & -6 \end{array} \right]$$

Subtract $-3 \times$ row 1 from row 3

$$\left[\begin{array}{ccc|c} 1 & 2 & -1 & 3 \\ 0 & -3 & 0 & -3 \\ 0 & 7 & -2 & 3 \end{array} \right]$$

and one more step to eliminate column 2.

$$\left[\begin{array}{ccc|c} 1 & 2 & -1 & 3 \\ 0 & -3 & 0 & -3 \\ 0 & 7 & -2 & 3 \end{array} \right]$$

Subtract $-\frac{7}{3} \times$ row 2 from row 3

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 2 & -1 & 3 \\ 0 & -3 & 0 & -3 \\ 0 & 0 & -2 & -4 \end{array} \right]$$

Returning to the equations:

$\phi_1(b)$

$$x + 2y - z = 3$$

$$-3y = -3$$

$$-2z = -4$$

we can solve for the variables.

$$x = 3 - 2y + z$$

$$-3y = -3$$

$$-2z = -4$$

The solution is $x = 3, y = 1,$

$$z = 2.$$

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Q1 (c) Apply Gaussian elimination with partial pivoting to solve the following system of equations. (5)

$$x_1 - x_2 + 3x_3 = -3.$$

$$-x_1 - 2x_3 = 1.$$

$$2x_1 + 2x_2 + 4x_3 = 0.$$

Soln

This example is written in tableau form as.

$$\left[\begin{array}{ccc|c} 1 & -1 & 3 & -3 \\ -1 & 0 & -2 & 1 \\ 2 & 2 & 4 & 0 \end{array} \right]$$

Under partial pivoting we compare $|a_{11}|=1$ with $|a_{21}|=1$ and $|a_{31}|=2$ and chose a_{31} for the new pivot. This is achieved through an exchange of rows 1 and 3.

$$\left[\begin{array}{ccc|c} 1 & -1 & 3 & -3 \\ -1 & 0 & -2 & 1 \\ 2 & 2 & 4 & 0 \end{array} \right] \rightarrow \text{exchange row 1 and row 3} \rightarrow \left[\begin{array}{ccc|c} 2 & 2 & 4 & 0 \\ -1 & 0 & -2 & 1 \\ 1 & -1 & 3 & -3 \end{array} \right]$$

$$\text{Sub. } -\frac{1}{2} \times \text{row 1.} \\ \text{from row 2.} \rightarrow \left[\begin{array}{ccc|c} 2 & 2 & 4 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & -1 & 3 & -3 \end{array} \right]$$

$$\text{Sub } \frac{1}{2} \times \text{row 1.} \\ \text{from row 3} \rightarrow \left[\begin{array}{ccc|c} 2 & 2 & 4 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & -2 & 1 & -3 \end{array} \right]$$

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Before eliminating column 2 we must compare the current $|a_{22}|$ with the current $|a_{32}|$. Because the latter is larger, we again switch rows.

$$\left[\begin{array}{ccc|c} 2 & 2 & 4 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & -2 & 1 & -3 \end{array} \right] \quad \text{exchange row 2} \\ \text{and row 3} \rightarrow \left[\begin{array}{ccc|c} 2 & 2 & 4 & 0 \\ 1 & 0 & -2 & 1 \\ 1 & -1 & 3 & -3 \end{array} \right]$$

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$$\text{Sub } -\frac{1}{2} \times \text{row 2} \\ \text{from row 3} \rightarrow \left[\begin{array}{ccc|c} 2 & 2 & 4 & 0 \\ 0 & -2 & 1 & -3 \\ 0 & 0 & \frac{1}{2} & -\frac{1}{2} \end{array} \right]$$

Q1(c)

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Note that all three multipliers are less than 1 in absolute value. The equations are now simple to solve. From

$$\frac{1}{2}x_3 = -\frac{1}{2}$$

$$-2x_2 + x_3 = -3$$

$$2x_1 + 2x_2 + 4x_3 = 0$$

we find that $x = [1, 1, -1]$.

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Q 2 (A) Apply Gauss-Seidal method to the following system.

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$$\begin{bmatrix} 3 & 1 & -1 \\ 2 & 4 & 1 \\ -1 & 2 & 5 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ 1 \end{bmatrix}$$

Solⁿ

The Gauss-Seidal iteration is

$$u_{k+1} = \frac{4 - v_k + w_k}{3}$$

$$v_{k+1} = \frac{1 - 2u_{k+1} - w_k}{4}$$

$$w_{k+1} = \frac{1 + u_{k+1} - 2v_{k+1}}{5}$$

Starting with $x_0 = [u_0, v_0, w_0] = [0, 0, 0]$.

we calculate

$$\begin{bmatrix} u_1 \\ v_1 \\ w_1 \end{bmatrix} = \begin{bmatrix} \frac{4 - 0 - 0}{3} = 4/3 \\ \frac{1 - 2(4/3) - 0}{4} = -5/12 \\ \frac{1 + 4/3 + 5/6}{5} = 19/20 \end{bmatrix} = \begin{bmatrix} 1.333 \\ -0.4167 \\ 0.6333 \end{bmatrix}$$

$$\begin{bmatrix} u_2 \\ v_2 \\ w_2 \end{bmatrix} = \begin{bmatrix} \frac{1.01}{60} \\ -3/4 \\ 251/300 \end{bmatrix} \approx \begin{bmatrix} 1.6833 \\ -0.7500 \\ 0.8367 \end{bmatrix}$$

The system is strictly diagonally dominant, and therefore the iteration will converge to the solution $[2, -1, 1]$.

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Q2 (b). Find the reduced QR factorization by applying Gram-Schmidt orthogonalization to the columns of the following matrix.

$$A = \begin{pmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{pmatrix}$$

Soln

set $y_1 = A_1 = \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}$ Then $r_{11} = \|y_1\|_2 = \sqrt{1+2+2} = 3$.

and the first unit vector is

$$q_1 = \frac{y_1}{\|y_1\|_2} = \begin{pmatrix} 1/3 \\ 2/3 \\ 2/3 \end{pmatrix}$$

To find the second unit vector, set

$$y_2 = A_2 - q_1 q_1^T A_2 = \begin{pmatrix} -4 \\ 3 \\ 2 \end{pmatrix} - \begin{pmatrix} 1/3 \\ 2/3 \\ 2/3 \end{pmatrix} 2 = \begin{pmatrix} -14/3 \\ 5/3 \\ 2/3 \end{pmatrix}$$

and $q_2 = \frac{y_2}{\|y_2\|_2} = \frac{1}{\sqrt{5}} \begin{pmatrix} -14/3 \\ 5/3 \\ 2/3 \end{pmatrix} = \begin{pmatrix} -14/\sqrt{15} \\ 1/\sqrt{3} \\ 2/\sqrt{15} \end{pmatrix}$

Since $r_{12} = q_1^T A_2 = 2$ and $r_{22} = \|y_2\|_2 = \sqrt{5}$

$$A = \begin{pmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{pmatrix} = \begin{pmatrix} 1/3 & -14/\sqrt{15} \\ 2/3 & 1/\sqrt{3} \\ 2/3 & 2/\sqrt{15} \end{pmatrix} \begin{pmatrix} 3 & 2 \\ 0 & \sqrt{5} \end{pmatrix} = QR$$

Q2(c) let $x = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$ and $w = \begin{pmatrix} 5 \\ 0 \end{pmatrix}$. (10)
find a Householder reflector H
that satisfies $Hx = w$.

Sol: $v = w - x = \begin{pmatrix} 5 \\ 0 \end{pmatrix} - \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 2 \\ -4 \end{pmatrix}$

and define the projection matrix.

$$P = \frac{vv^T}{v^T v} = \frac{1}{20} \begin{pmatrix} 4 & -8 \\ -8 & 16 \end{pmatrix} = \begin{pmatrix} 0.2 & -0.4 \\ -0.4 & 0.8 \end{pmatrix}$$

Then $H = I - 2P = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 0.4 & -0.8 \\ -0.8 & 1.6 \end{pmatrix} = \begin{pmatrix} 0.6 & 0.8 \\ 0.8 & -0.6 \end{pmatrix}$

check that H moves x to w and
vice versa.

$$Hx = \begin{pmatrix} 0.6 & 0.8 \\ 0.8 & -0.6 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 5 \\ 0 \end{pmatrix} = w$$

and $Hw = \begin{pmatrix} 0.6 & 0.8 \\ 0.8 & -0.6 \end{pmatrix} \begin{pmatrix} 5 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 4 \end{pmatrix} = x$

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(11)

Q3 (a) Find the Newton's method formula for the following equation.

$$x^3 + x - 1 = 0.$$

Sol:

Since $f'(x) = 3x^2 + 1$, the formula is given by

$$x_{i+1} = x_i - \frac{x_i^3 + x_i - 1}{3x_i^2 + 1}$$

$$= \frac{2x_i^3 + 1}{3x_i^2 + 1}$$

Iterating this formula from initial guess x_0

$x_0 = -0.7$ yields

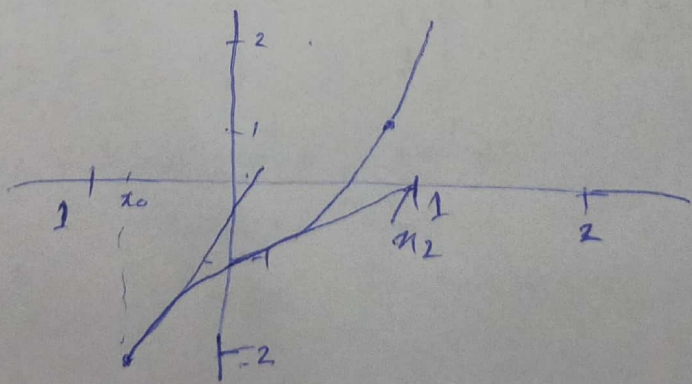
$$x_1 = \frac{2x_0^3 + 1}{3x_0^2 + 1} = \frac{2(-0.7)^3 + 1}{3(-0.7)^2 + 1} \approx 0.1271$$

$$x_2 = \frac{2x_1^3 + 1}{3x_1^2 + 1} \approx 0.9577$$

These steps are shown geometrically in fig 1.9 further steps are given in the following table.

i	x_i	$e_i = x_i - \alpha $	e_i / e_{i-1}^2
0	-0.70000000	1.38232780	
1	0.12712551	0.55520230	0.2906
2	0.95767812	0.27535032	0.8933
3	0.73482779	0.05249999	0.6924
4	0.68459177	0.00226397	0.8214
5	0.68233217	0.00000437	0.8527
6	0.68232780	0.00000000	0.85541
7	0.68232780	0.00000000	

After only six steps, the root is known to eight correct digits. There is a bit more we can say about the error and how fast it becomes small.

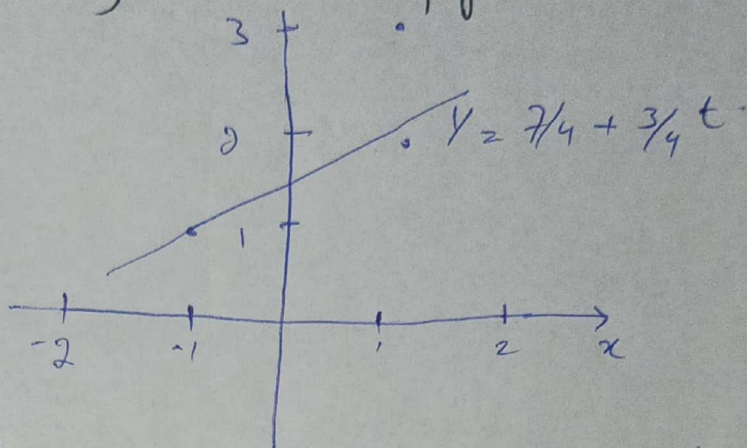


Q3(b)

(13)

Find the best line that fits -

the three data points $(t, y) = (1, 2), (-1, 1)$ and $(1, 3)$ in figure below.



Sol:

The model is $y = c_1 + c_2 t$ and the goal is to find the best c_1 and c_2 . Substitutions of data points into model yields

$$c_1 + c_2(1) = 2$$

$$c_1 + c_2(-1) = 1$$

$$c_1 + c_2(1) = 3$$

or in matrix form,

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$$

This system has no solution (c_1, c_2) for two separate reason the points are not collinear the equations are inconsistent. So the best solution in term of least square is

$(c_1, c_2) = (7/4, 3/4)$, Therefore the best

line is

$$y = 7/4 + 3/4 t$$

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