

Mid term paper.

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Section

'A'

Semester

7th Starting

Subject

Basic electromechanical

Submitted By

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Q :- 1/ Part (a)

Two well known formulae for calculating the total resistance of parallel connected resistance.

⇒ Formula for ^{only} two resistances

$$\frac{1}{R_{tot}} = \frac{1}{R_1} + \frac{1}{R_2}$$

⇒ Formula for any number of parallel resistances:-

$$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots + \frac{1}{R_N}$$

(2)

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Q No: 1 / Part B

Ans:- In Series Circuite, Resistance increase while Current decrease. Resistance is reciprocal of Conductance, if resistance increase automatically Conductance decreases.

$$R_{tot} = R_1 + R_2 + R_3 + \dots + R_n$$

$$\frac{1}{G_{tot}} = \frac{1}{G_1} + \frac{1}{G_2} + \frac{1}{G_3} + \dots + \frac{1}{G_n}$$

Now

In parallel Circuite

$$\frac{1}{R_{tot}} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots + \frac{1}{R_n}$$

So

$$G_{tot} = G_1 + G_2 + G_3 + \dots + G_n$$

In parallel Circuite Conductance increase

(3)

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while Resistance decrease.

$$\text{Conductance} \Rightarrow G = \frac{1}{R}$$

Q: 21

Given data:

$$R_1 = 3 \Omega$$

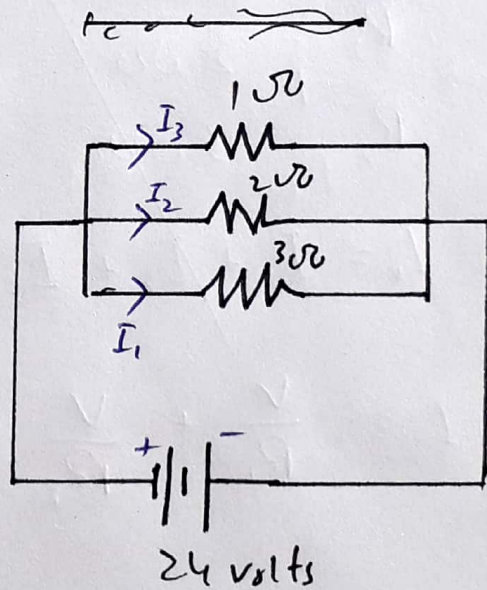
$$R_2 = 2 \Omega$$

$$R_3 = 1 \Omega$$

$$\text{Voltage} = V = 24 \text{ v}$$

$$I = ?$$

$$P = ?$$



Solution = Find current

1st Branch:

$$V = I_1 R_1$$

$$I_1 = \frac{V}{R_1} = \frac{24}{3} = 8$$

(4)

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ID = 7807

$$\boxed{I_1 = 8A} \Rightarrow \text{Current 1}$$

2nd Branch

$$I_2 = \frac{V}{R_2} = \frac{24}{2} = 12$$

$$\boxed{I_2 = 12A} \Rightarrow \text{Current 2}$$

3rd Branch:

$$I_3 = \frac{V}{R_3} = \frac{24}{1} = 24$$

$$\boxed{I_3 = 24A} \Rightarrow \text{Current 3}$$

Now find amount of power dissipated.

$$\boxed{P = I^2 R}$$

So

$$P_1 = I_1^2 R_1$$

(5)

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ID = 7807

$$P_1 = 8^3 \times 3$$

$$P_1 = 192 \text{ W}$$

$$P_2 = I_2^2 R_2$$

$$= 12^2 \times 2$$

$$P_2 = 288 \text{ W}$$

$$P_3 = I_3^2 R_3$$

$$P_3 = 24^2 \times 1$$

$$P_3 = 576 \text{ W}$$

(6)

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Q: 3.1 Differentiate:-

a) Current

⇒ Current is rate of flow of electric charges.

⇒ Its unit is Ampere

⇒ Current is effect and cannot flow without voltage

⇒ Current creates magnetic field

⇒ Current is same through all component connected in series.

⇒ Current get distributed over component connected in parallel

voltage

⇒ voltage also called e.m.f is energy per unit charges.

⇒ Its unit is volts.

⇒ voltage is cause and can exist without current.

⇒ voltage creates electrostatic field.

⇒ voltage get distributed over component connected in series.

⇒ voltage are same across all components connected in parallel.

(7)

Name = Rizwan Ullah Khan

ID = 7807

b) Resistance

⇒ Resistance is a property of a conductor which tell us how much resistor resist or opposes the current to pass through it.

⇒ Its unit is Ohm

$$\Rightarrow R = \frac{V}{I} \Rightarrow \frac{\text{voltage}}{\text{current}}$$

⇒ depend on length and thickness

conductance

⇒ Conductance is a property of conductor which tell us how much the resistor allow the current to pass through it.

⇒ Its unit is mho or Siemens.

$$\Rightarrow G = \frac{1}{R}$$

⇒ It is the reciprocal of resistance.

(8)

Name = Rijwan ullah Khan

ID = 7807

C) Energy

⇒ Energy is the Capacity to do work.

⇒ unit is Joule

⇒ Symbol is W

⇒ Energy changes from one form to another form.

⇒ Energy is known to be stored which can be used in future

⇒ Energy is used in cars, heating home, ~~at~~ Flying etc.

Power

⇒ Power is the rate at which work is done.

⇒ unit is watt.

⇒ Symbol is P

⇒ Power cannot be transferred from one type to another.

⇒ Power quantity is not storable.

⇒ Power uses in mechanical application, heat applications etc

(9)

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DI Inductance

- ⇒ Inductance is property of a current carrying conductor which generates a Φ magnetic field around the conductor.
- ⇒ An inductor only effect circuit when current is changing and will always oppose what is happening.
- ⇒ Unit of Inductance is Henry (H)

Capacitance:

- ⇒ Capacitance is a property of a device to hold and store electric charges.
- ⇒ More capacitance means more capacity to store charges.
- ⇒ Standard unit of capacitance is Farad (F)

E) Synchronous motor

- ⇒ Construction is complicated
- ⇒ Not self starting.
- ⇒ Separate DC source is required for rotor.
- ⇒ Speed control is not possible.
- ⇒ As load increase load angle ⁱⁿ increases.
- ⇒ It can be used as synchronous condenser for P-f improvement.

Asynchronous motor.

- ⇒ Construction is simpler
- ⇒ Self starting.
- ⇒ Rotor get excited by induced e.m.f so separate source not needed
- ⇒ Speed control is possible though difficult
- ⇒ As load increase speed keep on decreasing
- ⇒ It cannot be used as synchronous condenser
- ⇒ Phenomenon of hunting is absent.