

**Department of Electrical Engineering**  
**Assignment**

**Date: 27/06/2020**

**Course Details**

<b>Course Title:</b>	Power Electronics	<b>Module:</b>	
<b>Instructor:</b>	SIR SHAYAN TARIQ	<b>Total Marks:</b>	50

**Student Details**

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Note: Plagiarism of more than 20% will result in negative marking.  
Similar answers of students will result in cancellation of the answer for all parties.

Q1.	<p>Rectifiers are common circuits used in most electronic devices. There are multiple types of rectifiers used now a days. Explain in detail what are the similarities and differences between:</p> <ol style="list-style-type: none"><li>1. <math>1 - \phi</math> Uncontrolled Half Wave Rectifier and Full Wave Bridge Rectifier</li><li>2. <math>1 - \phi</math> Uncontrolled Rectifier and Controlled Rectifiers (Bridge Rectifier).</li></ol>	CLO 2  Marks 10
Q2.	<p>A AC voltage of <math>V_m = (\text{Last 2 digits of ID})</math> V has to be delivered to a Resistive DC load of <math>R = (\text{First 2 digits of ID})</math> ohms.</p> <p>The load and source are connected through 2 types of <math>1 - \phi</math> Uncontrolled rectifiers (Half Wave and Full Wave Bridge) and data is collected. Find the following for both rectifiers:</p> <ol style="list-style-type: none"><li>1. <math>V_{dc}</math></li><li>2. <math>I_{dc}</math></li><li>3. <math>V_{rms}</math></li><li>4. <math>I_{rms}</math></li><li>5. Which rectifier do you think is better and why.</li></ol>	CLO 2  Marks 10
Q3.	<p>The Buck chopper is a type of DC-DC converter. Explain in detail the principals and working of Buck converter when the switch is open and closed.</p> <p>The buck converter is connected to a DC source voltage of <math>V_{in} = 50V</math>. The duty cycle is <math>D = (\text{Last 2 digits of ID}) \%</math>, load of <math>R = (\text{First 2 digits of ID})</math> ohms and switching frequency of 20kHz. What will be the</p> <ol style="list-style-type: none"><li>1. <math>V_{out}</math></li><li>2. <math>I_{out}</math></li><li>3. <math>I_{in}</math></li><li>4. Inductor (L)</li></ol>	CLO 3  Marks 10

0Q4	<p>The Boost chopper is a type of DC-DC converter. Explain in detail the principals and working of Boost converter when the switch is open and closed.</p> <p>The boost converter is connected to a DC source voltage of <math>V_{in} = 50V</math>. The duty cycle is <math>D = (\text{Last 2 digits of ID}) \%</math>, load of <math>R = (\text{First 2 digits of ID})</math> ohms and switching frequency of 20kHz. What will be the</p> <ol style="list-style-type: none"> <li>1. <math>V_{out}</math></li> <li>2. <math>I_{out}</math></li> <li>3. <math>I_{in}</math></li> <li>4. Inductor (L)</li> </ol>	<p>CLO 3</p> <p>Marks 10</p>
Q5	<p>The Buck-Boost chopper is a type of DC-DC converter. Explain in detail the principals and working of Buck converter when the switch is open and closed.</p> <p>The Buck-Boost converter is connected to a DC source voltage of <math>V_{in} = 50V</math>. The Output voltage <math>V_{out} = (\text{Last 2 digits of ID}) \%</math>, load of <math>R = (\text{First 2 digits of ID})</math> ohms and switching frequency of 20kHz. What will be the</p> <ol style="list-style-type: none"> <li>1. Duty Cycle (D)</li> <li>2. <math>I_{out}</math></li> <li>3. <math>V_{in}</math></li> <li>4. Inductor (L)</li> </ol>	<p>CLO 3</p> <p>Marks 10</p>

①

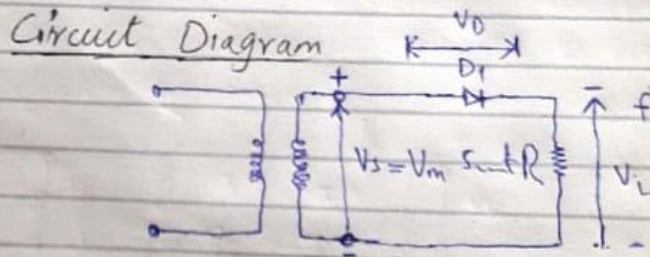
Q No 1

Rectifier

It is the electronic device which is used to convert AC into DC is called Rectifier.

### 1- $\Phi$ Uncontrolled Half Wave Rectifier

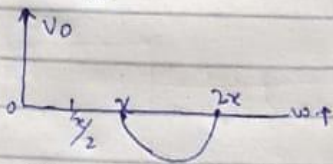
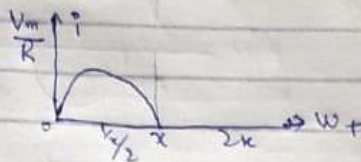
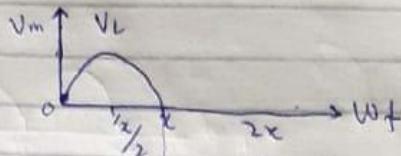
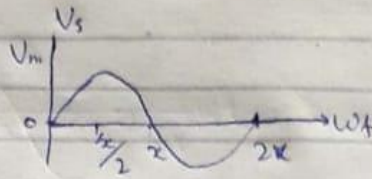
A Rectifier is a circuit that convert an ac signal into Unidirectional signal. Diodes are used commonly in rectifier. A single phase half wave rectifier is the simplest type is not normally used in industrial application. However, it is useful in understanding the principle of rectifier.



During positive half cycle the input voltage, diode  $D_1$  is forward biased and conduct. An input voltage appear across the load. During negative half cycle the input voltage the diode is blocking and output voltage is zero.

(2)

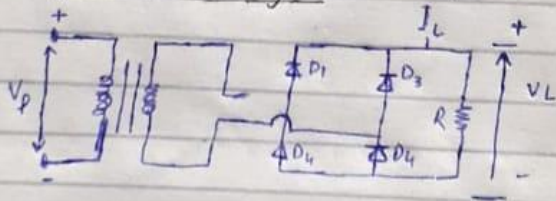
Waveform



1) 1- $\Phi$  Uncontrolled full wave bridge Rectifier

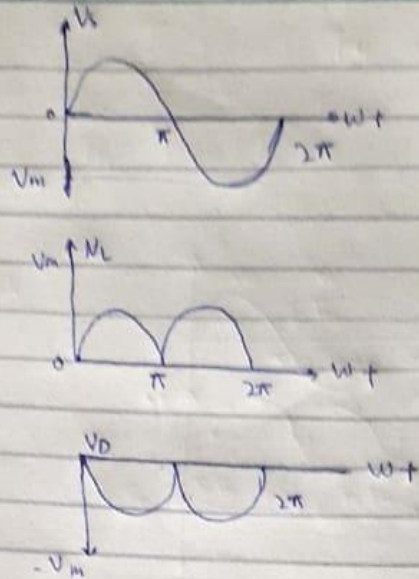
We use four diodes in bridge Rectifier circuit.

Circuit Diagram.



During positive half cycle of the input voltage the current flows through the load, through diode  $D_1$  and  $D_2$ . During negative cycle diode  $D_3$  and  $D_4$  conducts the peak inverse voltage of a diode is  $V_m$ .

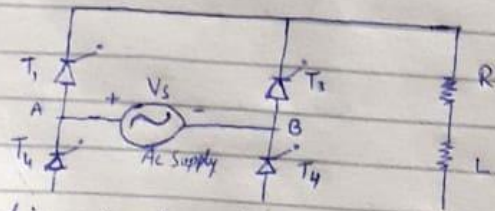
(3)



- Similarities and differences
- Both use diode
  - During positive half cycle both conduct.
  - During negative half cycle bridge Rectifier conduct but not conduct the half wave Rectifier

## 2. 1- $\phi$ Control bridge Rectifier

### Circuit Diagram

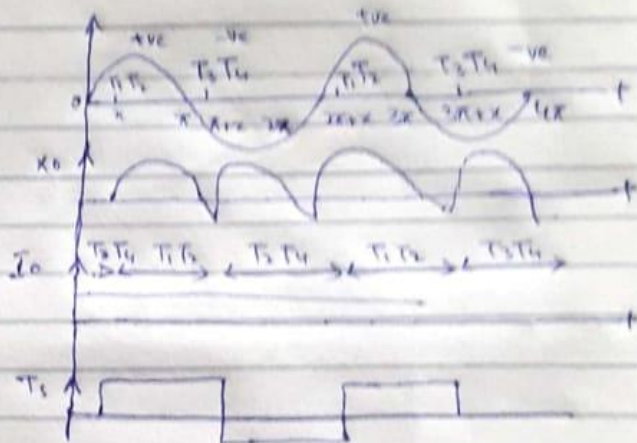


Its function is basically subdivided into two parts, positive half and negative half cycle. During positive half cycle  $T_1$  and  $T_2$  will become forward. If we give gate pulse to  $T_1$  and  $T_2$  current will flow in the loop. During negative half cycle

(1)

terminal B.  $T_3$  and  $T_4$  will be in forward bias. If we give gate pulse to  $T_3$  and  $T_4$  current will flow in another loop.

Graph:



Similarities and difference.

- Uncontrolled rectifier uses diodes
- Control rectifier uses SCR
- In control rectifier we use control the output by using the gate pulse. when we give gate pulse than it trigger otherwise not.

(5)

Q No 2

Soln-  $V_m = 01$

$$R = 12$$

We know that  
for half wave

1)  $V_{dc}$

$$\frac{V_m}{\pi} \rightarrow 0$$

$$V_m = 01, \pi = 3.14$$

So

$$\frac{01}{3.14} = 0.318V$$

For full wave

$$\frac{2V_m}{\pi}$$

$$\frac{2(01)}{3.14} = 0.636V$$

2)  $I_{dc}$

for half wave

$$I_{dc} = \frac{V_m}{\pi R}$$

$$= \frac{01}{3.14(12)} = 0.026A$$

(6)

For full wave

$$I_{dc} = \frac{I_m}{\pi}$$

$$I_m = \frac{V_m}{R}$$

$$= \frac{0.1}{12} = 0.83 A$$

So

$$I_{dc} = \frac{0.83}{3.14} = 0.264 A$$

3  $V_{rms}$

for half wave

$$V_{rms} = \frac{V_m}{2}$$

$$\frac{0.1}{2} = 0.5 V$$

For full wave

$$V_{rms} = \sqrt{2} V_s$$

$$\therefore V_s = \frac{V_m}{\sqrt{2}}$$

$$V_{rms} = \sqrt{2} (0.707)$$

$$= \frac{0.1}{\sqrt{2}} = 0.707 V$$

$$V_{rms} = 0.99 V$$

4  $I_{rms}$

for half wave

$$I_{rms} = \frac{V_m}{2R}$$



(7)

$$= \frac{01}{2(12)} = 0.041 \text{ A}$$

For full wave

$$\frac{I_m}{2} \rightarrow \textcircled{1} \quad \text{where} \quad I_m = \frac{V_m}{R}$$

$$= \frac{01}{12} = 0.083 \text{ A} \quad \text{put in } \textcircled{1}$$

$$\frac{I_m}{2} = \frac{0.083}{2} = 0.0415 \text{ A.}$$

S1 It would like to refer the uncontrol full wave bridge rectifier because the efficiency of the full bridge rectifier is better than half rectifier and output frequency also greater than half wave rectifier.

Q No 3:-

Principle of working of buck converter.

The main working principle of buck converter is that the inductor in the input circuit resist sudden variation in the input current when switch is ON. The inductor store energy in the form of magnetic energy and discharge it when the switch is closed. The capacitor in the output circuit is assumed large enough that the time constant of RC circuit in the output stage is high. The large time constant compare to switching period ensure a constant output voltage  $V_o(t) = V_o(\text{constant})$

Data:

12401

$$V_{in} = 50V$$

$$D = 0.01$$

$$R = 12$$

$$\text{frequency} = 20\text{kHz}$$

①  $V_{out}$ 

$$V_{out} = D \times V_s \rightarrow \text{①}$$

 $d = \text{Duty cycle}$ 

$$0.01\% = 0.0001 \text{ put in ①}$$

$$(0.0001)(50) = 0.5V$$

2)  $I_{out}$

$$I_o = \frac{V_o}{R}$$

$$\frac{0.5}{12} = 0.051A$$

3)  $I_{in}$

We know that

$$I_o = \frac{I_i}{\alpha \text{ or } D}$$

$$I_i = I_o \times \alpha$$

where  $\alpha$  is a duty cycle

$$I_i = 0.051A \times 0.03$$

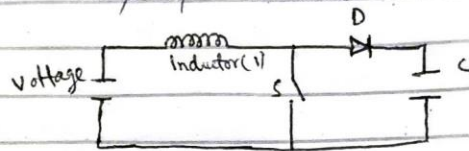
$$I_{in} = 0.00051A$$

4) Inductor.

Q No 4

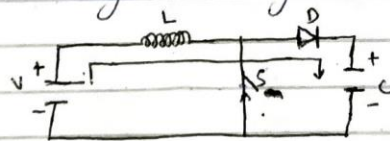
Boost converter:

A boost converter is one of the simplest type of switch mode converter. It takes an input voltage and boost it. All consist of is an inductor, a semi conductor switch, a diode and a capacitor. It is also called as step-up converter.

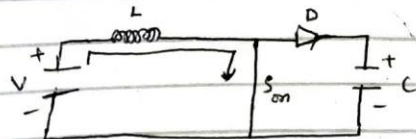


Working Principle:

The main working principle of main converter is that the inductor in the input circuit resist sudden variations in input current. When switch is off the inductor stores energy in the form of magnetic energy and discharges it when switch is closed. The capacitor in the output circuit is assumed large enough that the time constant of R.C circuit in the output stage is high.



The output capacitor is charged to the input voltage minus one diode drop



When the switch is on our signal source goes high, turning on the MOSFET. All the current is diverted through to the MOSFET through the inductor. The output capacitor stays charged since it can't discharge through the now back-biased diode.

The switch is ON and therefore represents a short circuit ideally offering zero resistance to the flow of current. Let us say the switch is ON for a time  $t_{ON}$  & is OFF for a time  $t_{OFF}$ . We define the time period,

frequency  $T$ , as  $T = t_{ON} + t_{OFF}$  & the switching frequency

$$f_{switch} = \frac{1}{T}$$

Now define another term duty cycle.

$$D = \frac{t_{ON}}{T}$$

Boost converter is steady state operation for this made using KVL

$$V_{in} = V_L$$

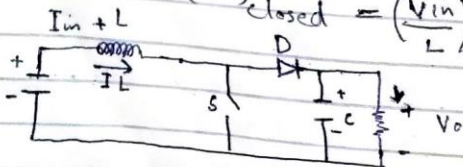
$$V_L = L \frac{di_L}{dt} = V_{in}$$

$$\frac{di_L}{dt} = \frac{\Delta i_L}{\Delta t} = \frac{\Delta i_L}{DT} = \frac{V_{in}}{L}$$

Since the switch is closed for a time.

$$t_{ON} = DT \text{ we can say that } \Delta t = DT$$

$$(\Delta i_L)_{closed} = \left(\frac{V_{in}}{L}\right) DT$$



In this mode, the polarity of the inductor is reversed. The energy stored in the inductor is released and is ultimately dissipated in the load resistance, & this helps to maintain the flow of current in the same direction, through the load and also step up the voltage as the inductor is now also acting as a source in conjunction with the input source.

Analyse the circuit using KVL  
Boost converter is steady state operation for mode 2 using KVL

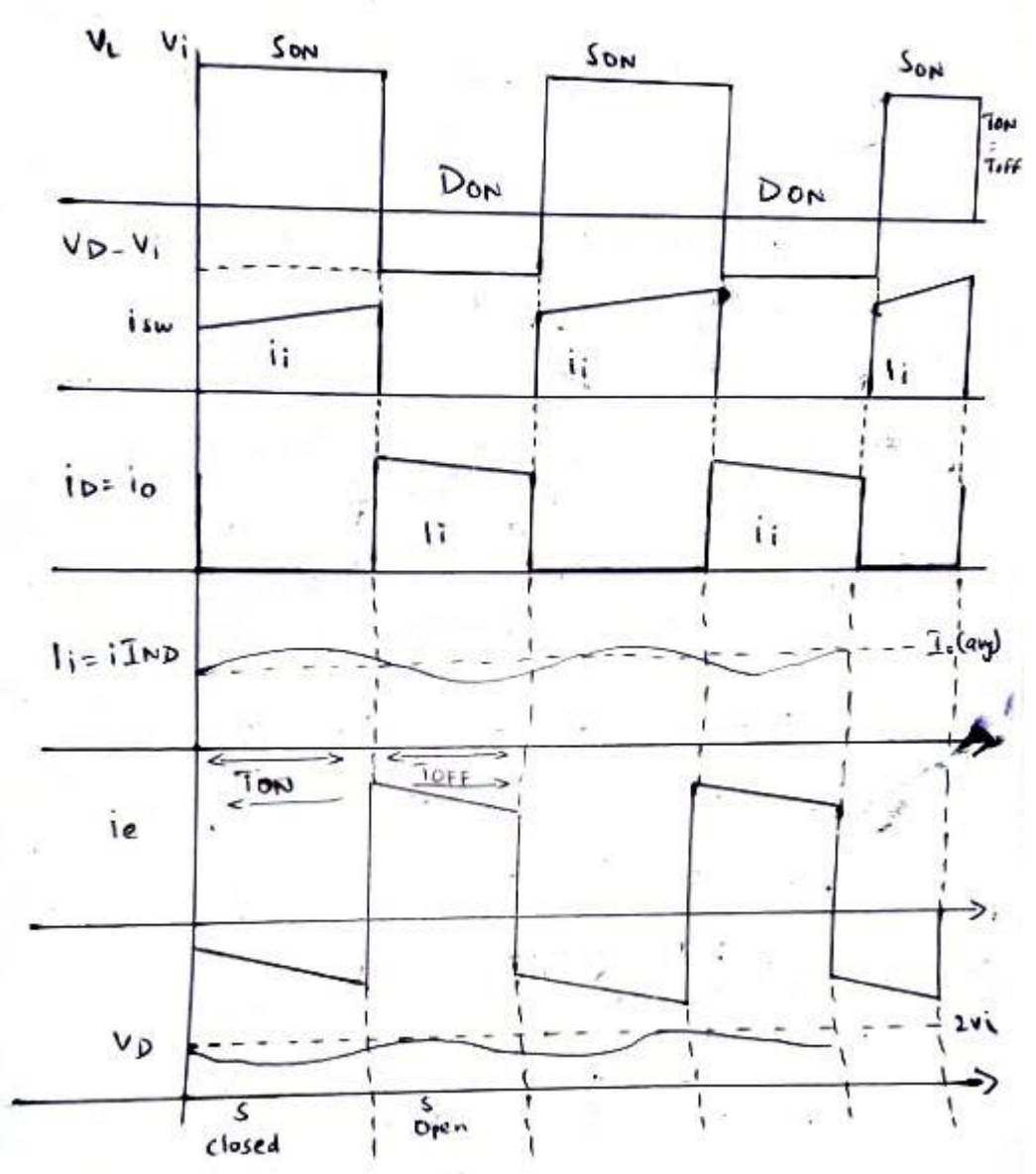
$$V_{in} = V_L + V_o$$

$$V_L = \frac{v di_L}{dt} = V_{in} - V_o$$

$$\frac{di_L}{dt} = \frac{\Delta i_L}{\Delta t} = \frac{\Delta i_L}{(1-D)T} = \frac{V_{in} - V_o}{L}$$

Since the switch is open for a time  $T_{OFF} = T - T_{ON} = T - DT = (1-D)T$  we can say that  $\Delta t = (1-D)T$

(7)

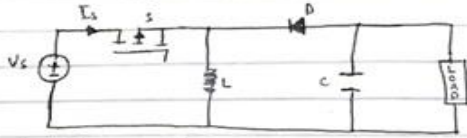


QNO5

## Buck-Boost Choppers

A buck boost converter which can operate as a DC-DC step-down upon the duty cycle,  $D$ .

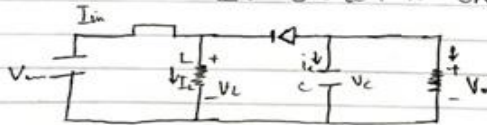
Buck-Boost Converter is shown below



The input voltage source is converted to a solid state device. The second switch is used a diode. The diode is connected, in reverse to the direction of power flow from source, to a capacitor and the load and the two are connected in parallel as shown in the figure above.

The controlled switch is turned ON and OFF by using pulse with modulation. PWM can be time based or frequency based. Time based is mostly used for DC-DC converters. It is simple to construct and use. Frequency remain constant in this type of PWM modulation.

Mode 1: Switch is ON, Diode OFF

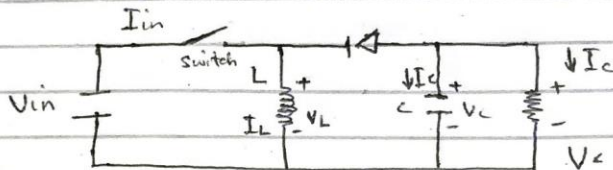


The switch is ON and therefore represent a short circuit ideally offering zero resistance to the flow of current. So when the switch is ON all the current will flow through the switch and and the



inductor and back to the DC input source. The inductor stores charge during the time the switch is ON & when the solid state switch is OFF the polarity of the inductor reverses, so that current flows through the load and through the diode and back to the inductor. So the direction of the current remain same.

MODE II. Switch is OFF, Diode is ON



In this mode the polarity of the inductor is reversed and the energy stored in the inductor is released. So the current through the inductor cannot abruptly change the diode must carry the current so it commutates and begins conducting. Energy is transformed from the inductor to the capacitor resulting in a decreasing inductor current and a voltage across the resistor with the opposite polarity compared to  $V_{in}$ .

During steady state the circuit is said to operate.

- 1- In discontinuous ~~condition~~ conduction mode if the inductor current reaches zero.
- 2- In continuous conduction mode if the inductor current never reaches zero.

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Data:

$$V_{in} = 50V$$

$$V_{out} = 0.1\%$$

$$\text{Resistor} = 12$$

$$\text{frequency} = 20\text{kHz}$$

① Duty Cycle

$$\frac{V_o}{V_i} = \frac{-D}{1-D}$$

$$V_o = +V_i d$$

$$= 1-d$$

$$0.01 = +50 \frac{d}{1-d}$$

$$(0.01)(1-d) = 50d$$

$$0.01 = 50d + 0.01d$$

$$0.01 - 0.01d = 50d$$

$$0.01 = 50.01d$$

$$\frac{0.01}{(50)(0.01)} = 0.000002$$

2 || $I_{out}$ 

$$I_{max} + I_{min} = \frac{2dv}{R(1-d)^2}$$

$$I_{max} + I_{min} = \frac{2(0.000002)(50)}{12(1-0.000002)^2}$$

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$$= \frac{0.0002}{11.99} = 1.66^{-5}$$

$$I_{out} = \frac{I_{max} + I_{min}}{2}$$

$$\frac{1.66^{-5}}{2} = 0.039 A$$

3)  $I_i = ?$

$$I_i = I_{cd}$$

$$= 0.039 \times 1.66^{-5}$$

$$= 0.0030 A.$$